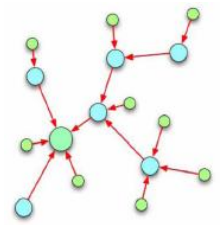


Wireless Sensor and Actuator Networks: *Technologies, Analysis and Design*

Network Connectivity for WSANs

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Topology Control versus Connectivity Control

Topology Control aims at controlling the set of links that connect couples of nodes, in order to simplify routing of messages / allow routing of messages between all pairs of nodes.

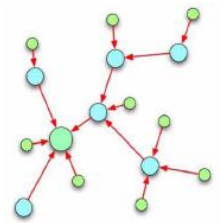
The **physical topology** of a network can be controlled through physical layer, in most cases power control techniques are used.

The **logical topology** of a network is controlled by entities working at layer 2 and 3, and is based on a **reduced set of links** wrt the physical topology.

Logical topologies can be *flat* or **hierarchical** according to the roles assigned to nodes.

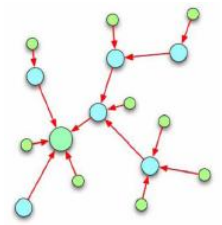
Connectivity Theory aims at describing the potential topologies of a networks, assuming nodes are randomly distributed over space.

It deals mainly with physical topologies, but can be extended to some aspects of logical topologies taking non-electromagnetic aspects into account like for instance capacities, interference, etc.



Outline

- 1. Network Topologies in WSNs**
- 2. Connectivity Theory: Preliminaries**
- 3. Critical Transmission Range**
- 4. Connectivity Over an Unlimited Region**
- 5. Connectivity for WSNs**
- 6. Connectivity Over Limited Regions for WSNs**



Background: Elements of Graph Theory

Geometric Graph (GG)

Vertices have a geometric location in \mathbf{R}^d . In the following we assume $d=2$.

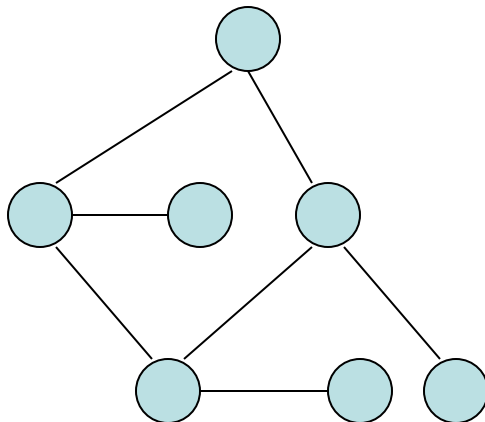
Random Graph

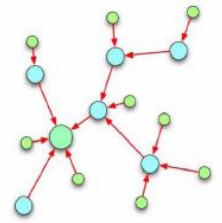
Edges between pairs of nodes exist according to random statistics.

Geometric Random Graph (GRG)

Random Graph where edges exist according to proximity relation between nodes and nodes are in unknown positions.

In GRGs, the set of nodes is normally finite, and their number deterministically known.





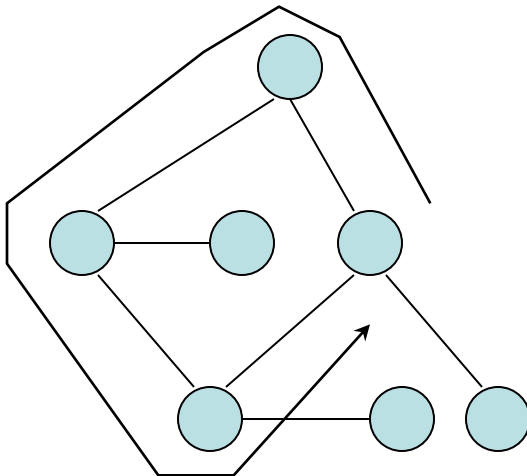
Background: Elements of Graph Theory

Complete Graph

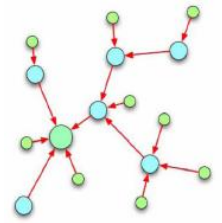
An *undirected graph* with an *edge* between every pair of *vertices*

Acyclic Graph

A *graph* with no *path* that starts and ends at the same *vertex*.



Not complete
Not acyclic



Background: Elements of Graph Theory

Connected Graph

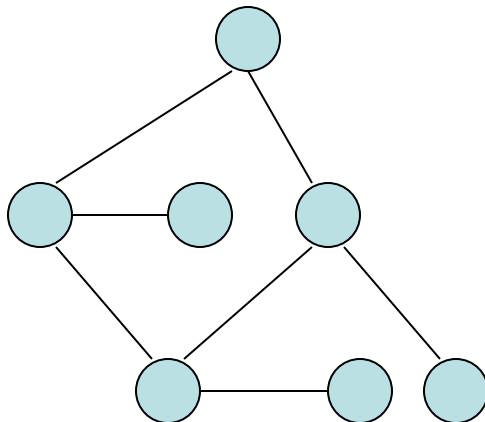
An *undirected graph* that has a *path* between every pair of *vertices*.

Edge Connectivity

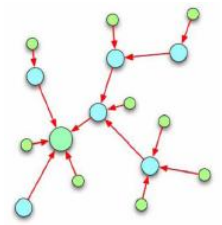
The smallest number of *edges* whose deletion will cause a *connected graph* to not be connected.

Node Connectivity

The smallest number of *vertices* whose deletion causes a *connected graph* to not be connected.



Connected
EC=1
NC=1



Background: Elements of Graph Theory

The Communication Graph

A Network is a pair (N,L)

N is a set of wireless nodes, of size n . Assume they are located in an unit square.

L is the function mapping every node u to a position $L(u)$.

A **Range Assignment** is a function assigning to every node u a transmit range $RA(u)$.

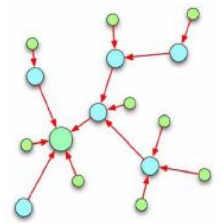
The Communication Graph is the directed graph (G,E) where the directed edge (u,v) exists if the Euclidean distance between u and v is less or equal than $RA(u)$.

In this case v is neighbour to u . If u is also neighbour to v for all pairs (u,v) , the Communication Graph is undirected and all links are symmetrical.

A RA for a Network is **connecting** if the correspondent CG is connected.

A RA where all nodes have the same transmit range is said **homogeneous**.

If the value of the transmit range R is relevant, than the RA is said **R-homogeneous**.



Background: Elements of Graph Theory

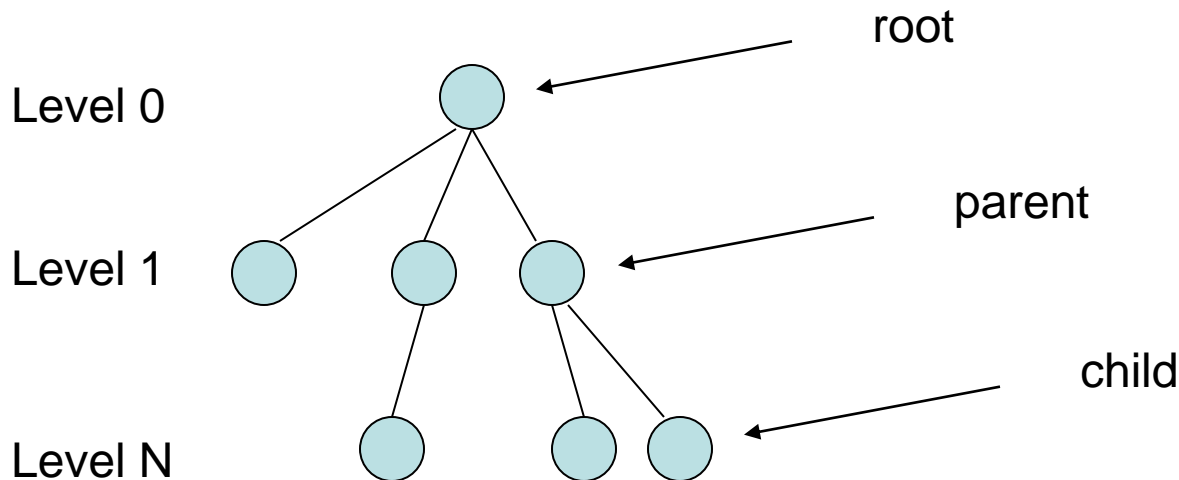
Tree

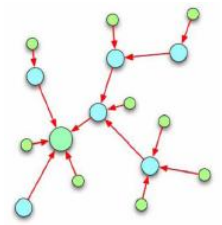
A *connected, undirected, acyclic graph*.

It is a data structure accessed beginning at the *root* node, where each *node* is either a *leaf* or an *internal node*.

An internal node has one or more *child* nodes and is called the *parent* of its child nodes. All children of the same node are *siblings*.

Contrary to a physical tree, the root is usually depicted at the top of the structure, and the leaves are depicted at the bottom.





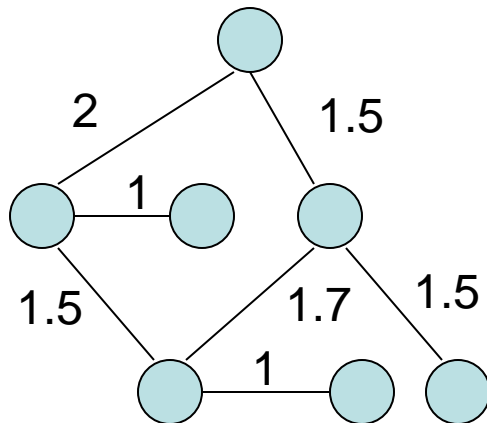
Background: Elements of Graph Theory

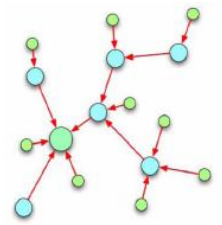
Weighted Graph

A *graph* having a weight, or number, associated with each *edge*

Euclidean Tree

A *tree* in a weighted GG where weights are assigned to edges based on Euclidean distances.





Background: Elements of Graph Theory

Spanning Tree

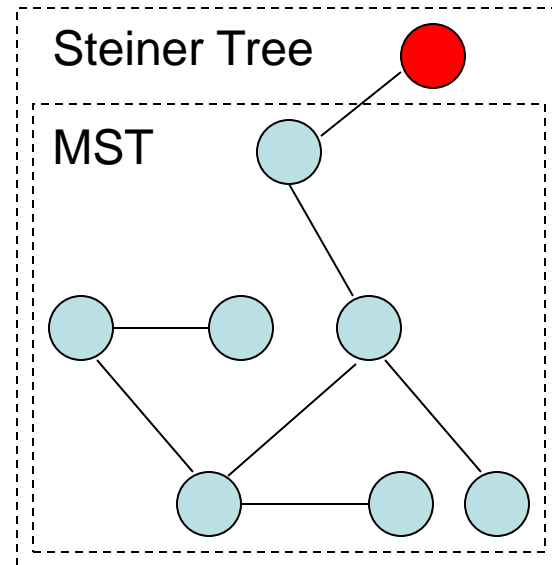
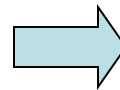
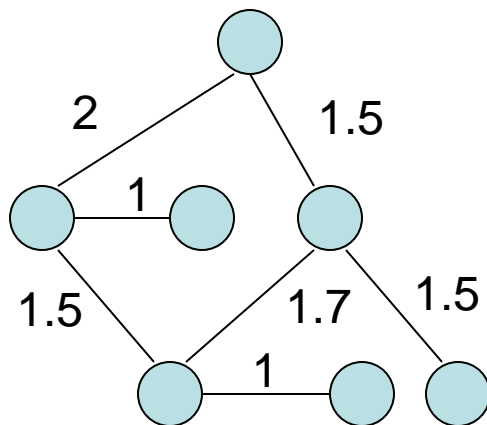
A connected, acyclic subgraph containing all the vertices of a graph

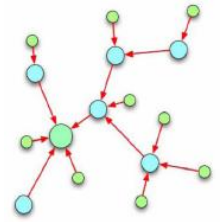
Minimum Spanning Tree (MST)

A minimum-weight tree in a weighted graph which contains all of the graph's vertices.

Steiner Tree

A minimum-weight *tree* connecting a designated set of *vertices*, called *terminals*, in an *undirected, weighted graph*. The tree may include non-terminals, which are called *Steiner vertices*.

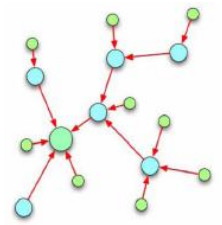




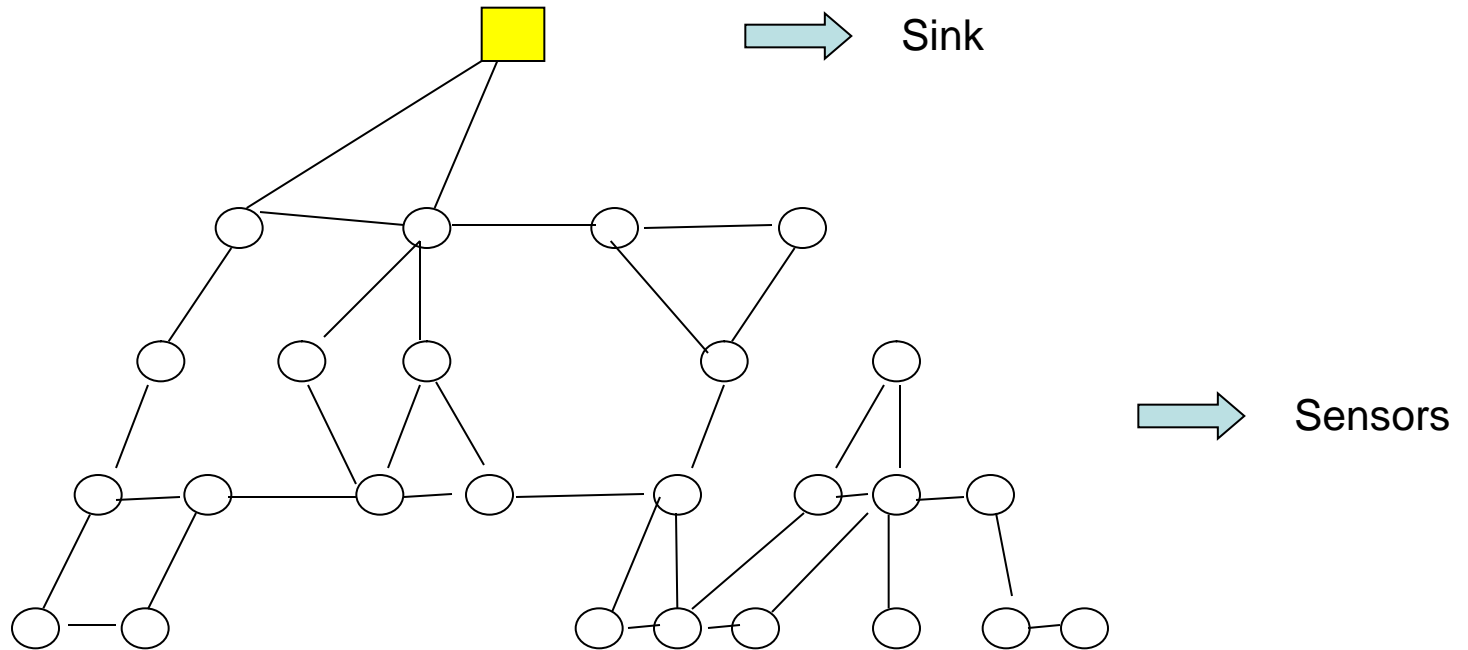
Section 1

Network Topologies in WSNs

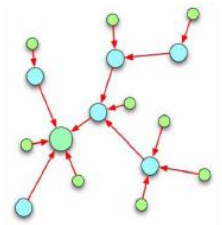
Flat
Trees
Optimised Tree Design



Flat

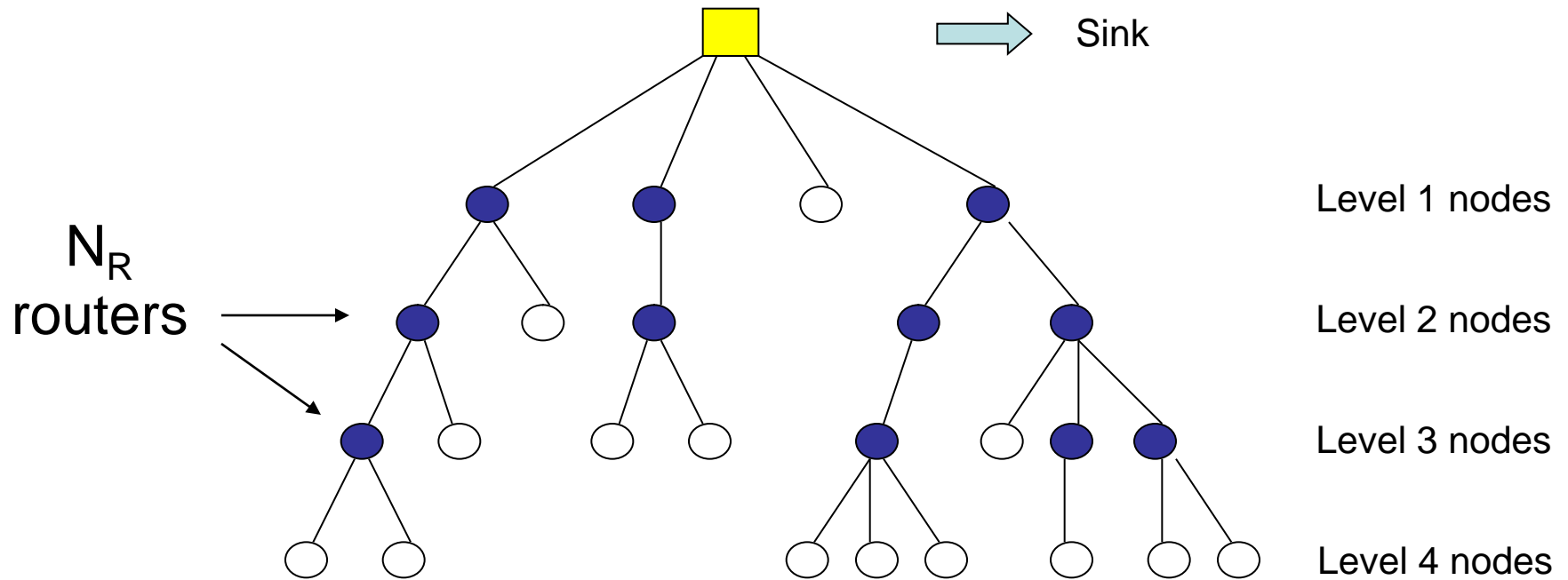


With 802.15.4, the NBE mode should be used.



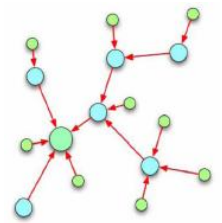
Trees

PAN Coordinator



With 802.15.4 BE mode:

$$2^{BO} \geq (N_R + 1) \cdot 2^{SO}$$



Trees

Pros

Routing is simple

Local Addressing is a simple task

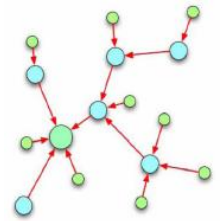
Few parameters allow control of the topology

Data aggregation strategies are simplified

Cons

Large average delays

Critical Links



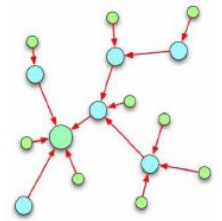
**Owing to the type of information flow,
trees (hierarchical topologies)
are the most appropriate.**

**For the sake of energy efficiency,
the role of nodes must be often rotated.**

Topologies are thus inherently dynamic.

**Some applications include moving sensors
and the topologies are consequently
very dynamic.**

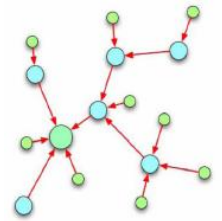
**Efficiency of Topology Reconfiguration mechanisms
is a key issue.**



Section 2

Connectivity Theory: Preliminaries

What does it aim to
Link Connectivity
Full Connectivity
Critical Transmission Range

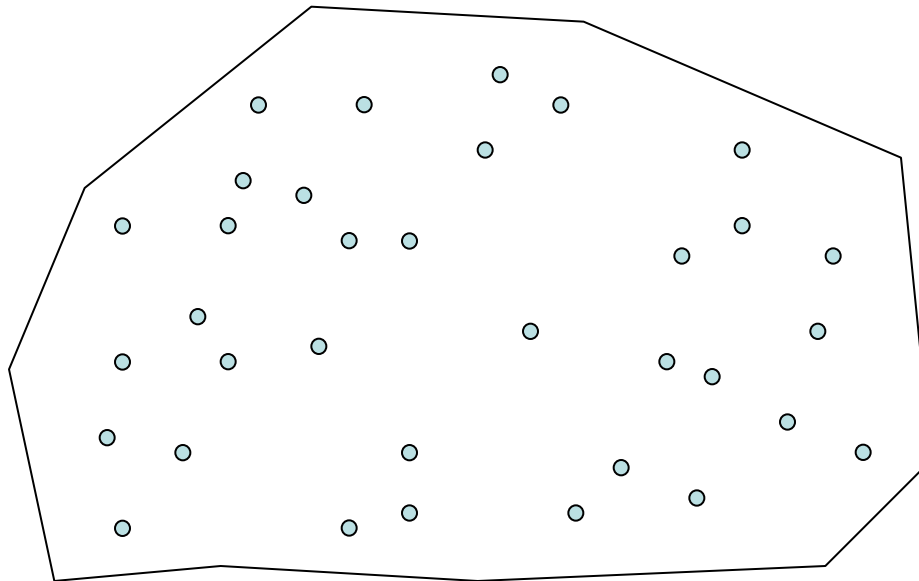


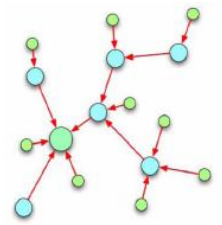
What does it aim to

In networks formed by large numbers of nodes distributed according to some **statistics** over a limited or unlimited region of \mathbf{R}^d , Connectivity Theory aims at describing the potential set of links that can connect nodes to each other, subject to some constraints from the physical viewpoint (power budget, or radio resource limitations).

It studies network properties

$d = 2$ is considered here.





Poisson Point Process (PPP)

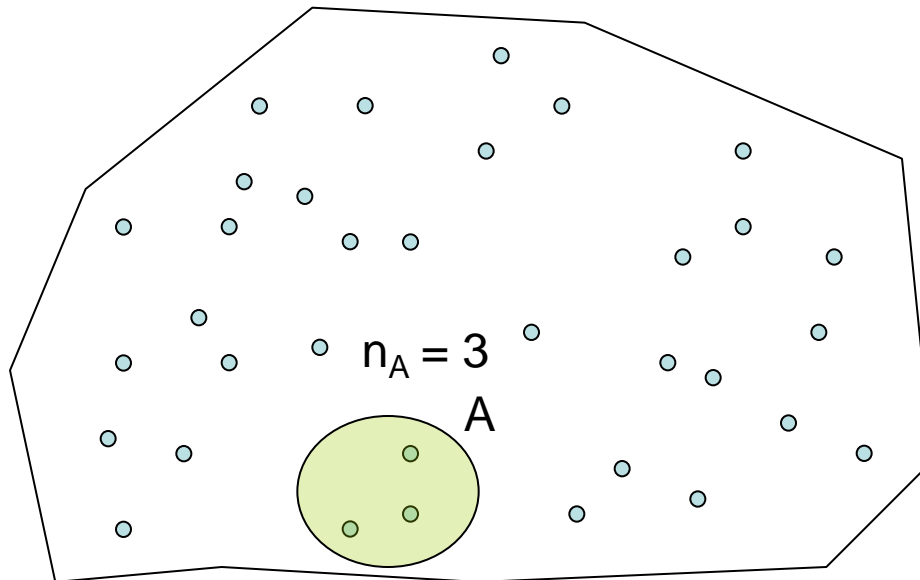
Given a (sub-)region A , the number of nodes in A , n_A , is Poisson, with mean $N_A = \rho A$ where ρ is node density.

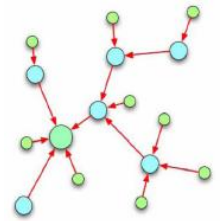
This is equivalent to **random and uniform independent positions of nodes.**

$$\text{Prob}(n_A = n) = e^{-\rho A} (\rho A)^n / n! = e^{-N_A} (N_A)^n / n!$$

The probability that the region is empty is $\text{Prob}(n_A = 0) = e^{-\rho A} = e^{-N_A}$

PPPs may be considered either on bounded or unbounded regions.

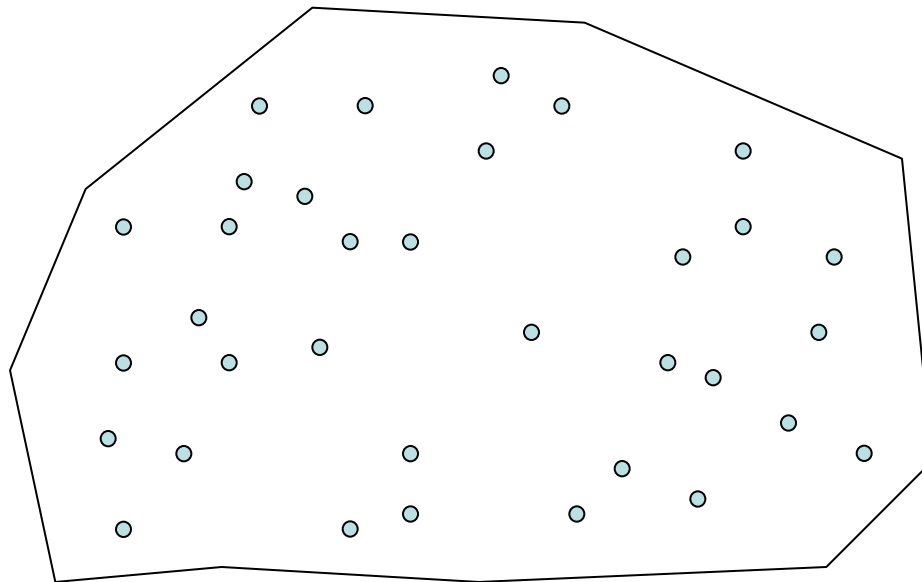


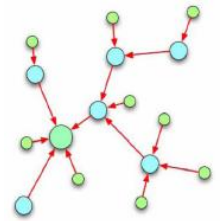


What does it aim to Examples

What is the probability that the network is **fully connected**
(i.e. every node can reach any other node through any number of hops)
when nodes are distributed in the region according to a PPP with intensity ρ .

Relevant in ad hoc nets.

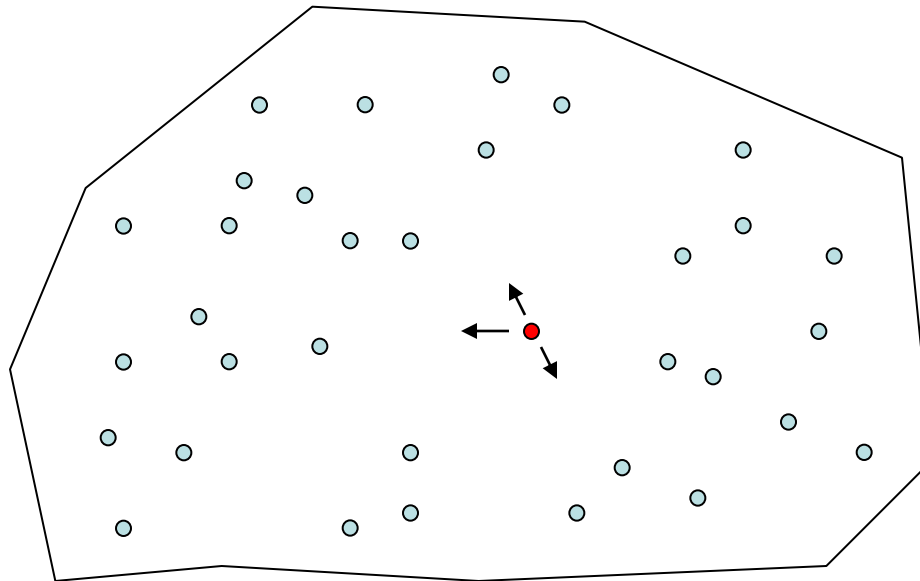


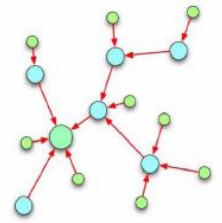


What does it aim to Examples

What is the probability that **a node is isolated**
when nodes are distributed in the region according to a PPP with intensity ρ .

Relevant in WSNs.

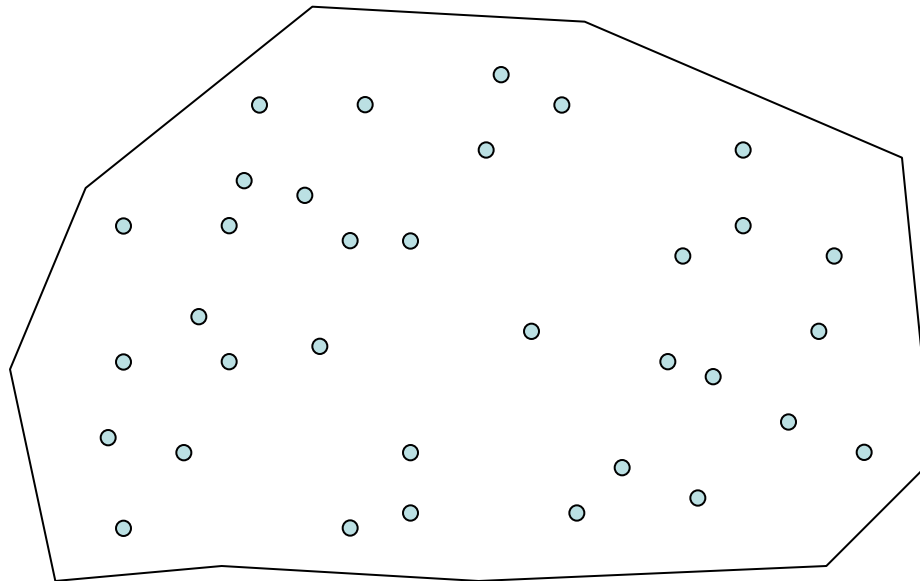


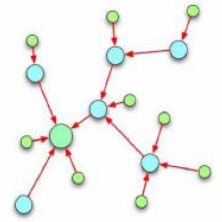


Regions

In the literature, typically three types of statistical scenarios are considered:

- Square of unit side (or disk of unit radius) with nodes distributed in the region according to a PPP with intensity ρ ;
- A PPP with intensity ρ over an unbounded region;
- Square of unit side (or disk of unit radius) with N (N is given) nodes uniformly distributed at random in the region.



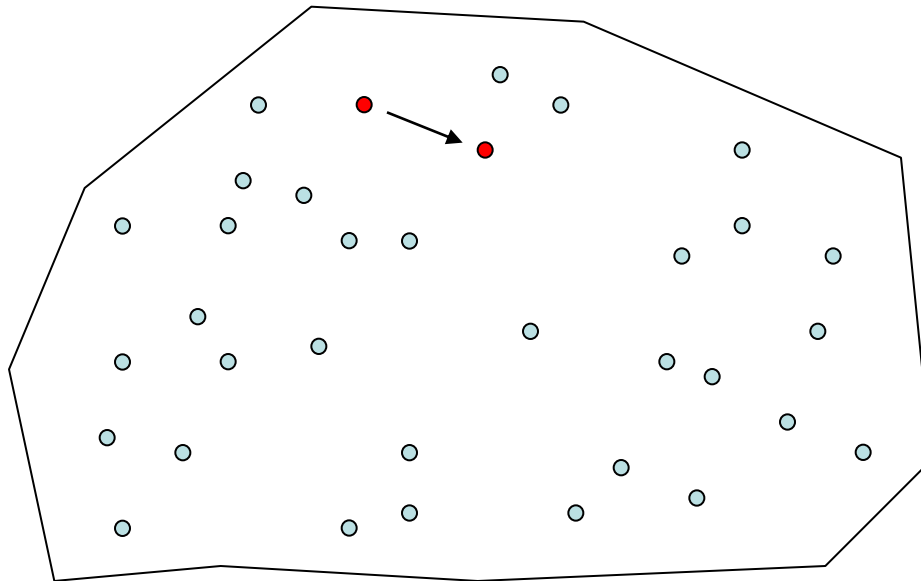


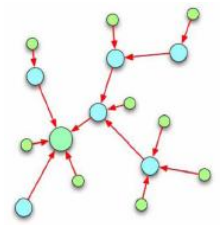
Link Connectivity

To study (network) connectivity, one has to define link connectivity properties.

Different models in the literature, all considering narrowband systems.

Can be used for 802.15.4, Bluetooth.



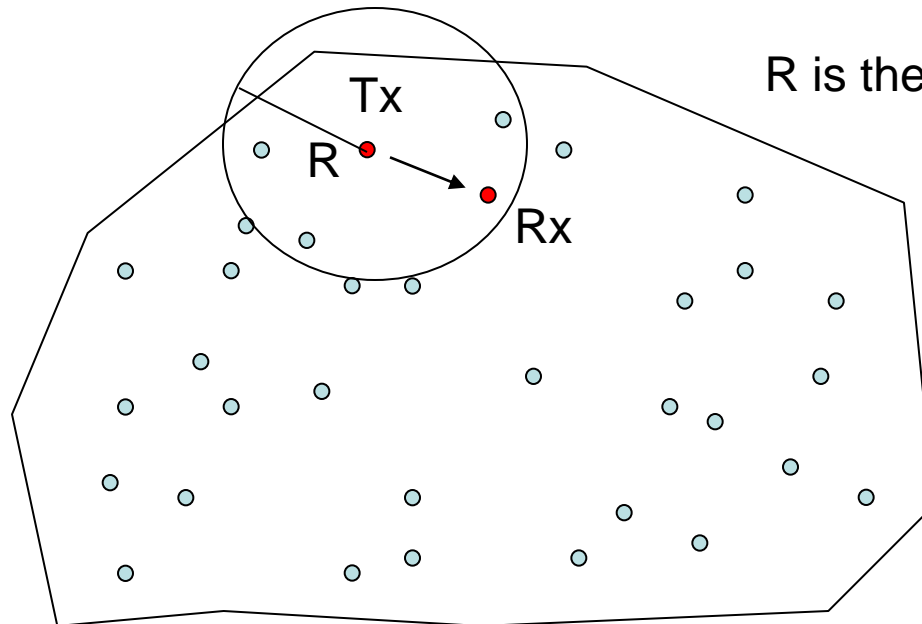


Link Connectivity

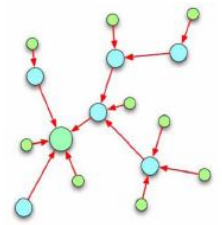
Model 1 (deterministic distance - dependent model). The most widely used.

Rx is connected to Tx

- if SNR is above minimum threshold α , i.e.
- if received power P_r is above minimum threshold P_{rmin} , i.e.
- if power loss L is smaller than maximum value L_{th}
and $L = k_0 + k_d \log r$ i.e.
- if distance r is below a given maximum value R



R is the transmitting range.



Link Connectivity

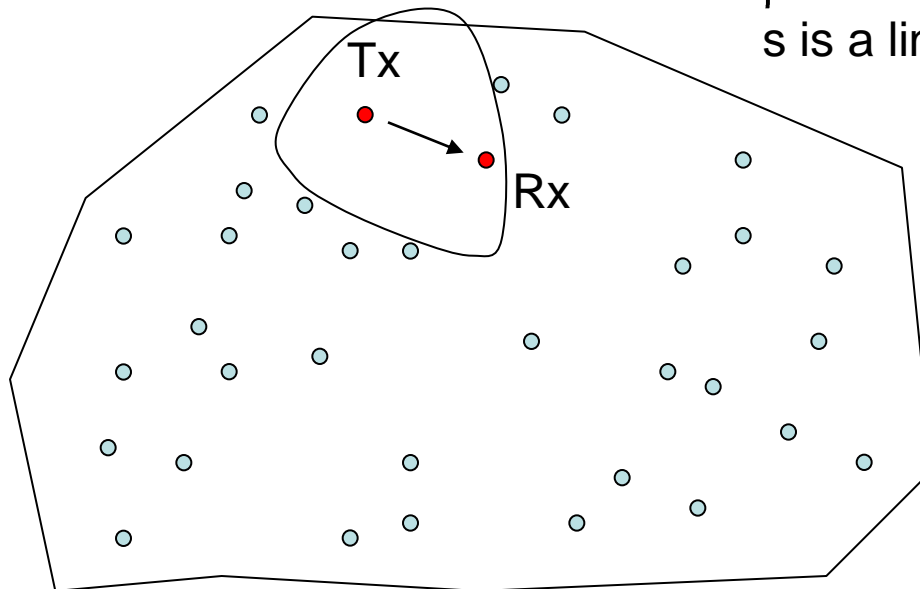
Model 2 (random distance - dependent model). Used in the following.

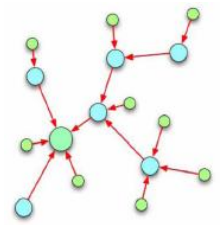
Rx is connected to Tx if SNR is above minimum threshold α , i.e.
if received power P_r is above minimum threshold P_{rmin} , i.e.
if power loss L is smaller than maximum value L_{th}

$$\text{and } L = k_0 + k_d \log r + s$$

$$k_d = 10 \beta$$

β is the propagation exponent
 s is a link-dependent r.v.



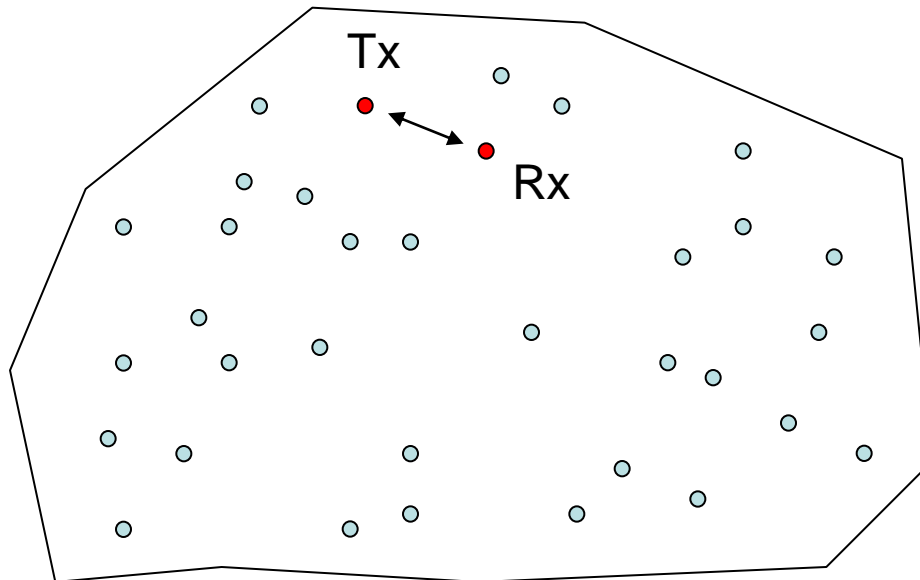


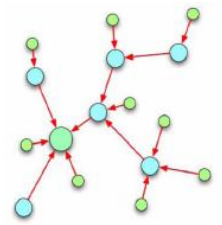
Link Connectivity

We adopt **Model 2**, with s modelled as zero mean Gaussian r.v. with variance σ^2 .

$$L = k_0 + k_1 \ln r + s \quad k_1 = k_d / \ln 10$$

When variance of s is zero, Model 2 converges to Model 1.

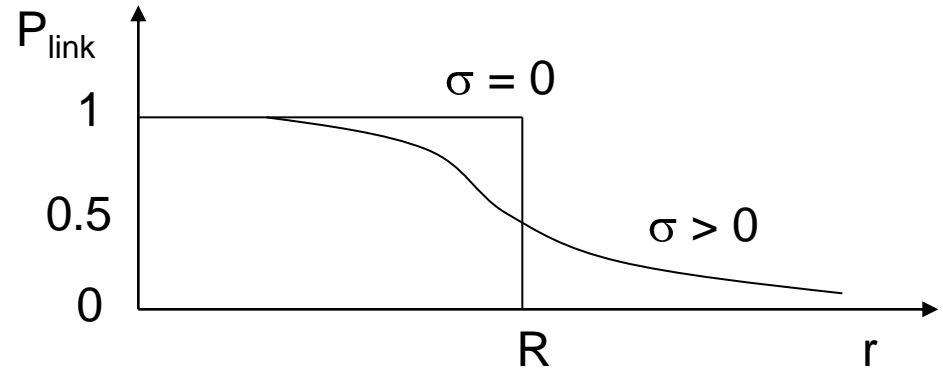




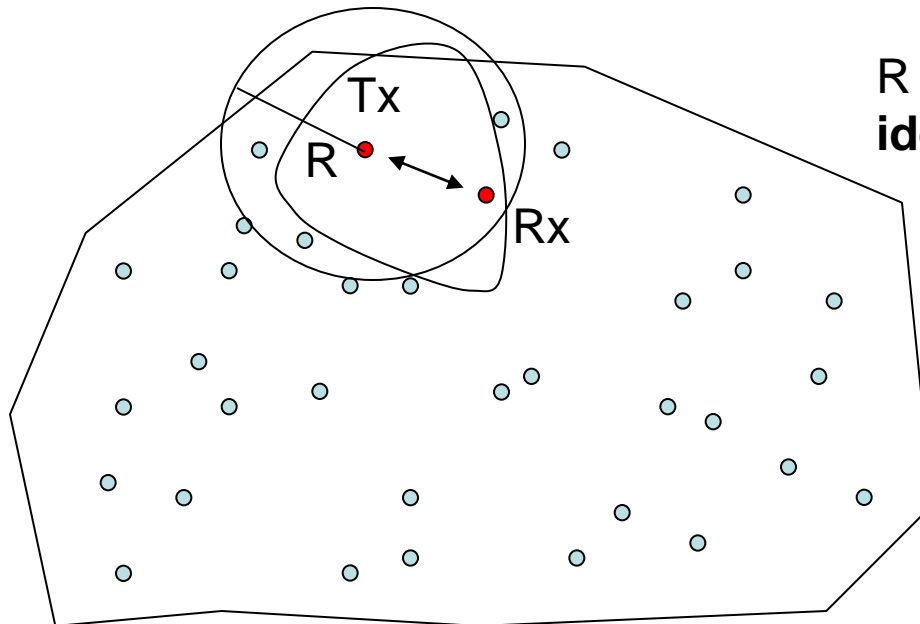
Link Connectivity

$$P_{link} = \Pr\{L(dB) < L_{th}\} = \Pr\{s < L_{th} - k_0 - k_1 \ln(r)\} =$$

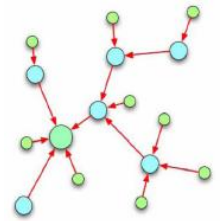
$$= \frac{1}{2} + \frac{1}{2} \operatorname{erf}\left(\frac{L_{th} - k_0 - k_1 \ln(r)}{\sqrt{2}\sigma}\right)$$



R is the
ideal transmission range



$$R = \exp((L_{th} - k_0)/k_1)$$



Full Connectivity

Traditional definition:

A network is fully connected if there exists any path (sequence of hops) between every pair of nodes.

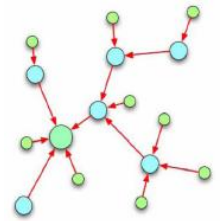
This definition is compliant with the objective of ad hoc networks, i.e. to allow every node being in contact with any other node.

But this is not the goal of a WSN.

In WSNs, nodes (sensors) want to transmit their samples to a given node, namely, the sink (or any node in a given set, in the case of multi-sink networks).

Definition more suitable for WSNs:

A WSN is fully connected if all nodes can report their samples to a sink through any path.

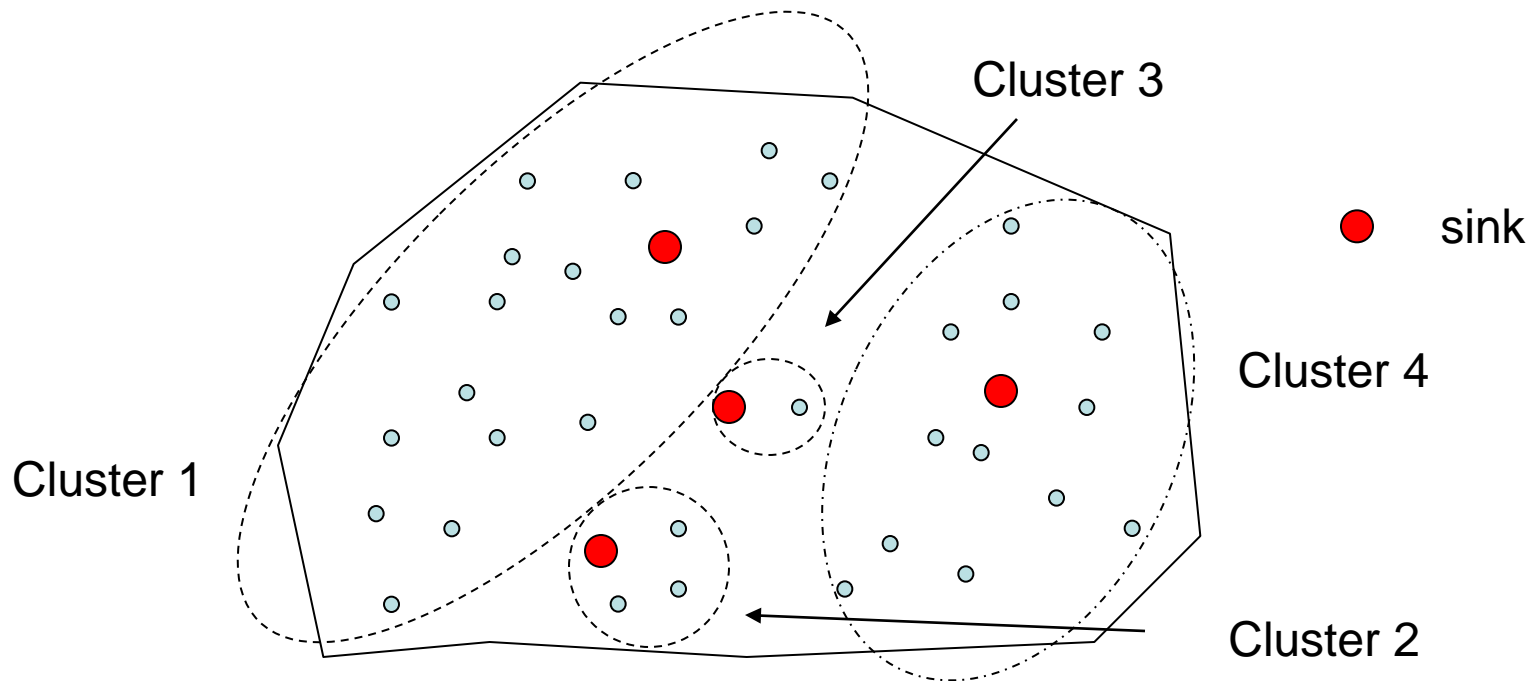


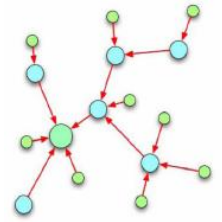
Full Connectivity

Note that under such new definition, a WSN can be fully connected even if some nodes can not reach other nodes, in a multi-sink scenario.

In other words, a WSN can be fully connected even if clustered.

The difference is relevant for finite (and small) densities.

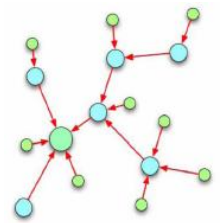




Section 3

Critical Transmission Range

Critical Transmission Range
The Giant Component



Critical Transmission Range

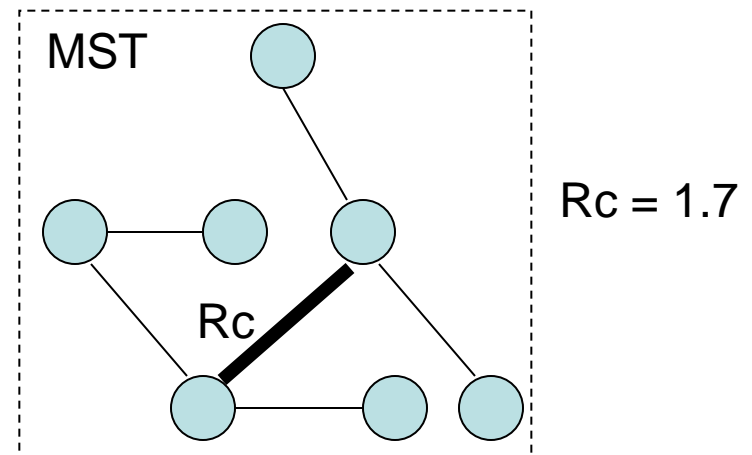
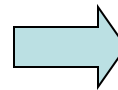
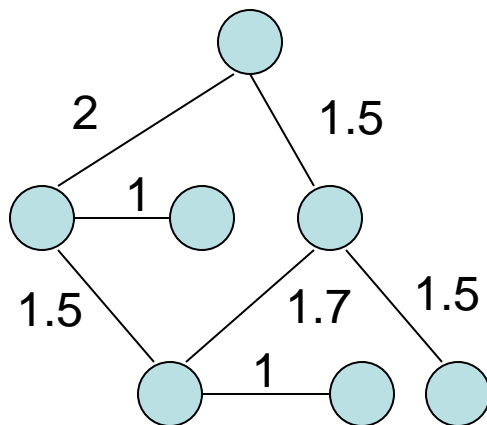
Critical Transmission Range:

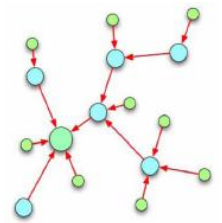
The minimum value of R for a Network s. t. the network is fully connected.

If the nodes in the Network are randomly distributed, the CTR is a random variable.

Theorem:

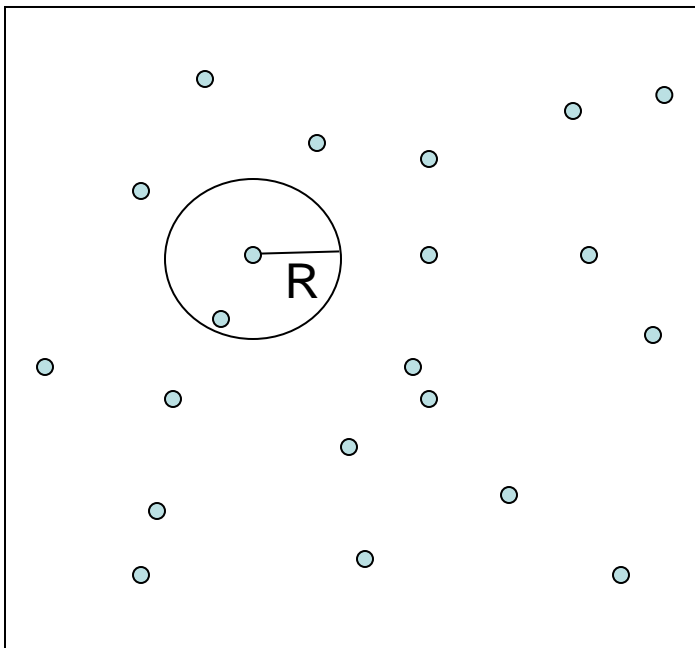
The CTR for connectivity R_c of a Network equals the length of the longest edge of the Euclidean MST of the corresponding Communication Graph





Critical Transmission Range

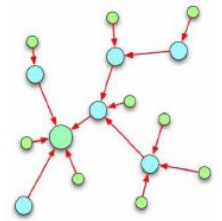
Unit square



n number of nodes

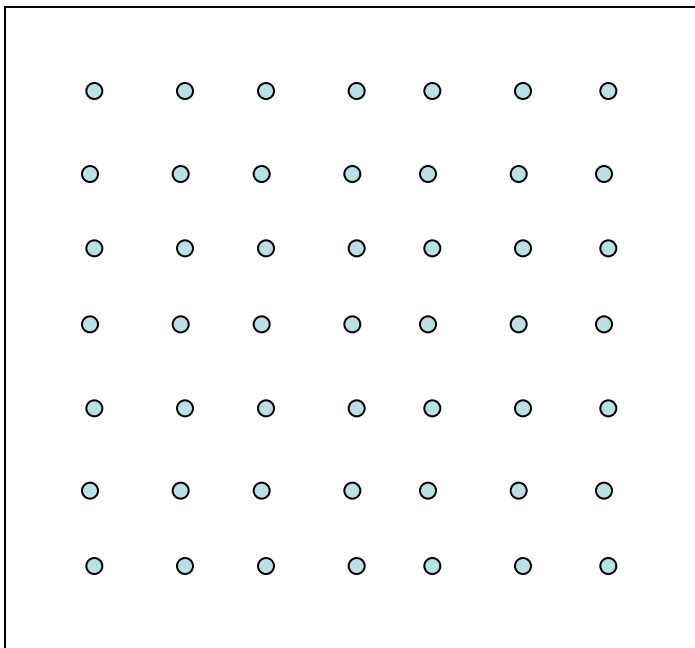
→ node density is $n / 1 = n$

R transmission range



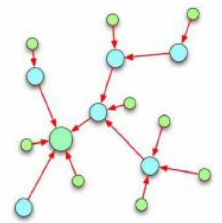
Critical Transmission Range

Unit square



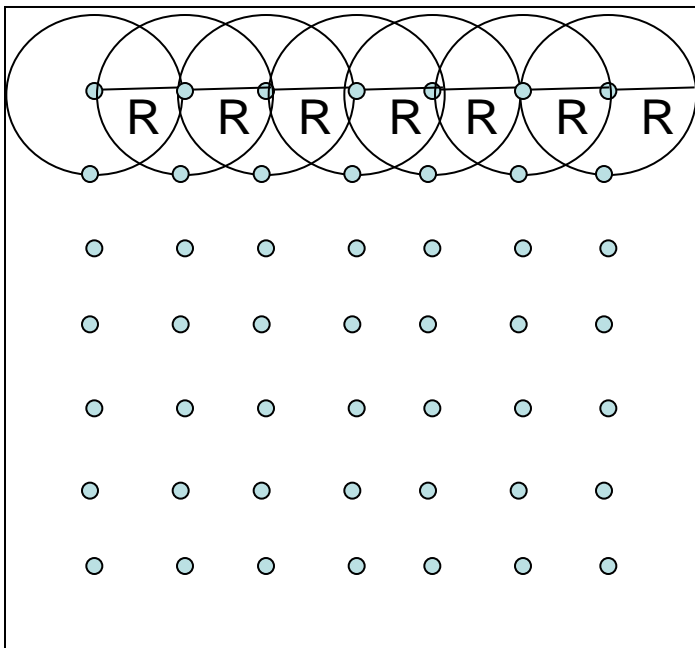
$n = 49$

Regular grid as reference



Critical Transmission Range

Unit square



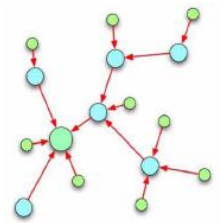
CTR:

$$R \text{ s.t. } R [\text{sqrt}(n) + 1] = 1$$

$$\rightarrow \text{CTR} = 1 / [\text{sqrt}(n) + 1]$$

In a square of side L

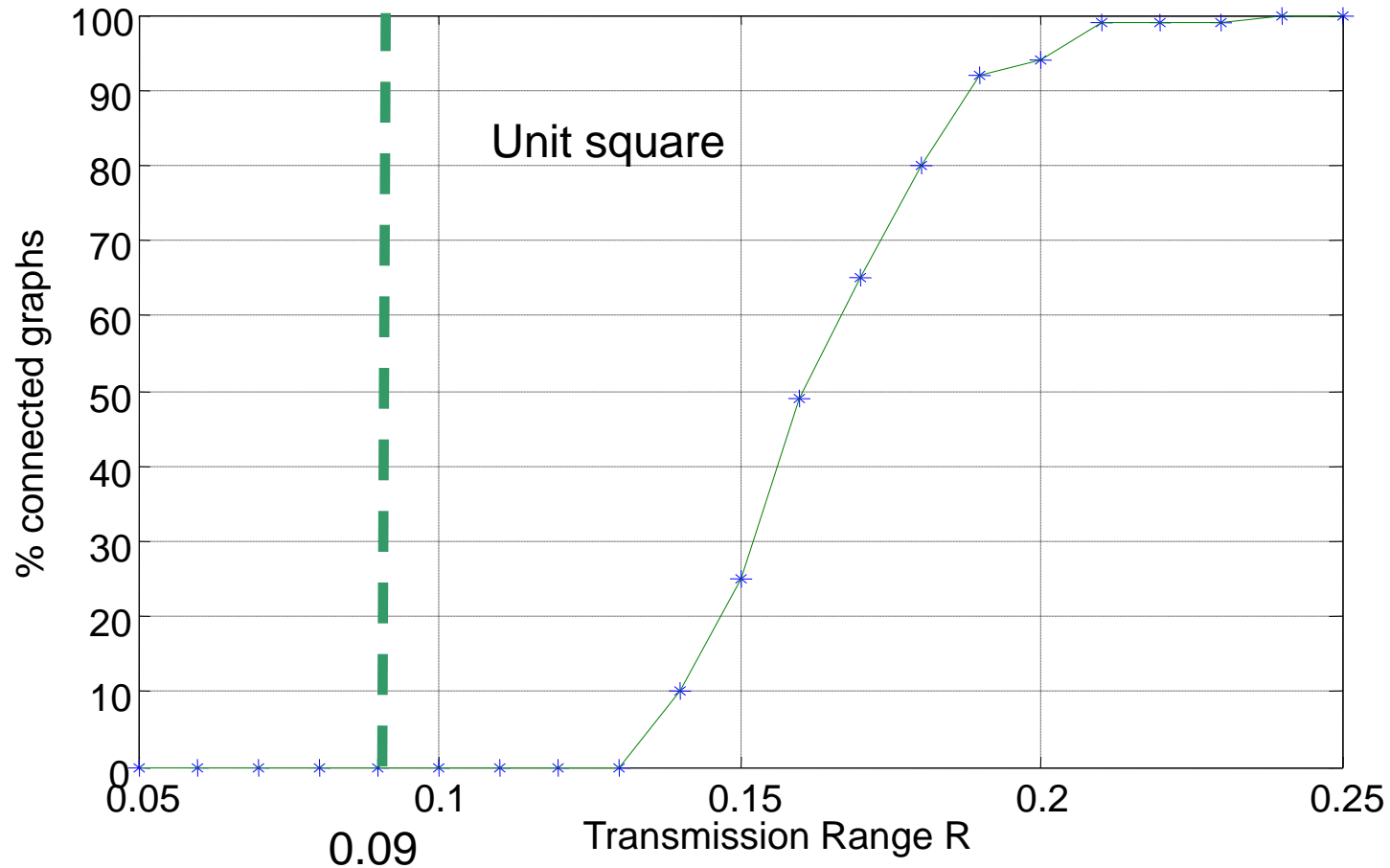
$$\rightarrow \text{CTR} = L / [\text{sqrt}(n) + 1]$$



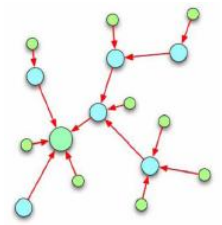
Critical Transmission Range

$n = 100 \rightarrow$ CTR = 0.09 in a regular grid

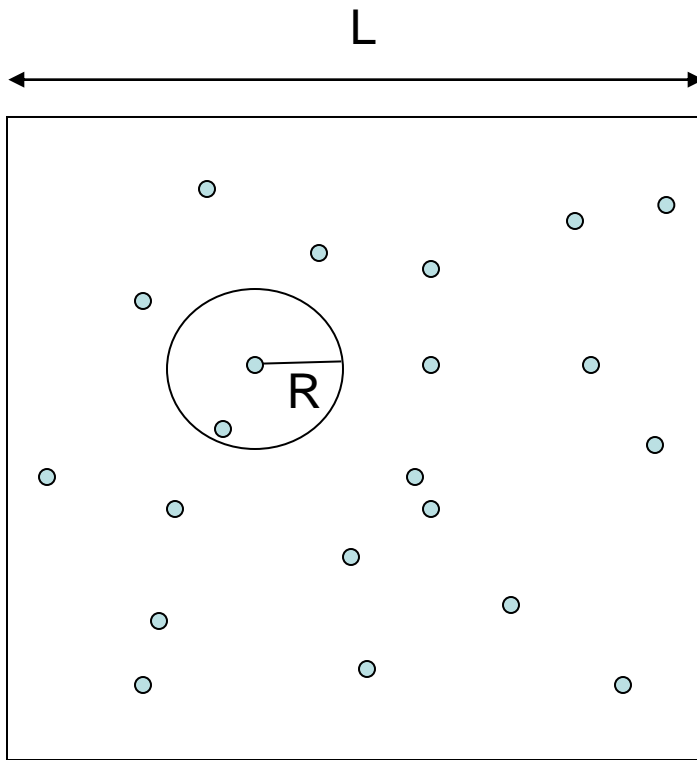
100 graphs



Randomness of node position has a significant impact on connectivity issues



Critical Transmission Range

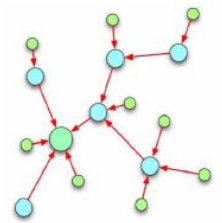


n number of nodes

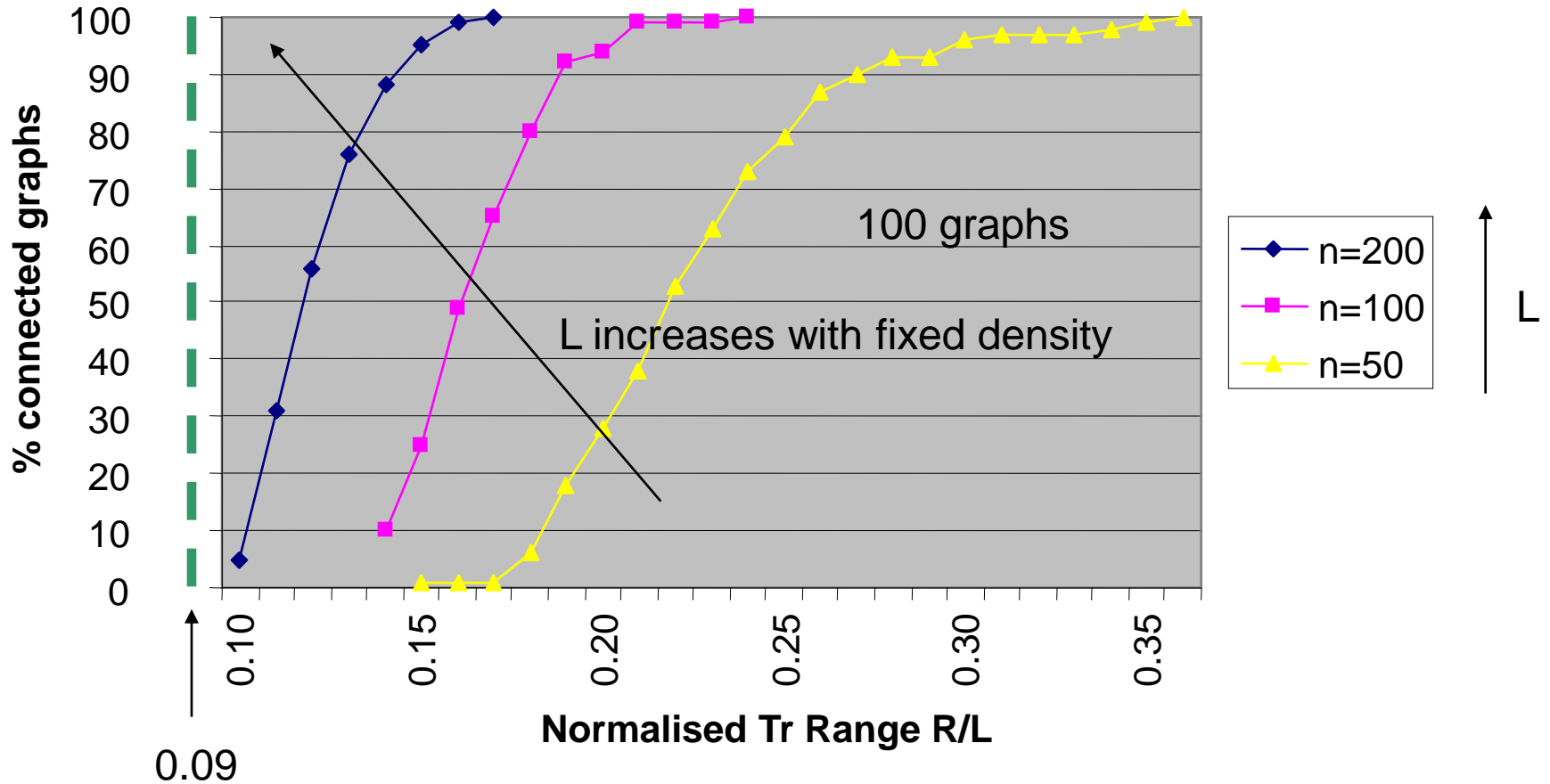
→ node density is n / L^2

→ $n = \rho L^2$

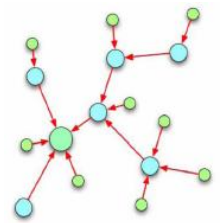
R transmission range



Critical Transmission Range



Size of scenario has a significant impact on connectivity issues



Critical Transmission Range

Theorem (Penrose 1997):

Given the unit square and n nodes distributed randomly and uniformly, then the limit for n tending to infinity of

Prob [$n\pi (R_c)^2 - \log n \leq b$]

is

$1 / \exp(\exp(-b))$

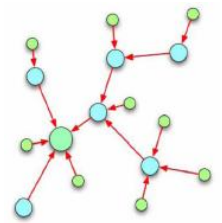
for any b in \mathbf{R} where R_c is the CTR.

As a corollary, for n tending to infinity we have (choose b tending to infinity)

Prob [$R_c \leq \sqrt{(b + \log n) / n\pi}$] = 1.

In other words, **$\sqrt{(b + \log n) / n\pi}$** is an upper bound to R_c for n tending to infinity and since it tends to zero for proper selections of b , it is a very tight upper bound.

For finite values of n , this expression does not necessarily represent an upper bound.



Critical Transmission Range

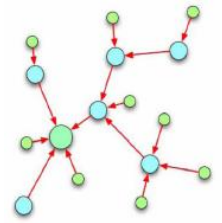
For which values of n are the predicted values of R_c accurate?

For instance, with $b = \log \log n$

n	R_c (Penrose)	R_c (sim., 99% conf)	$R_c = 1 / [\sqrt{n} + 1]$
10	0.32	0.66	0.24
100	0.14	0,23	0.09
1000	0.05	0.08	0.03

Not very accurate for practical values of n .

Considerations for n tending to infinite are often unrealistic for practical values of node densities



The Giant Component

Consider a given graph, and let R increase starting from 0.

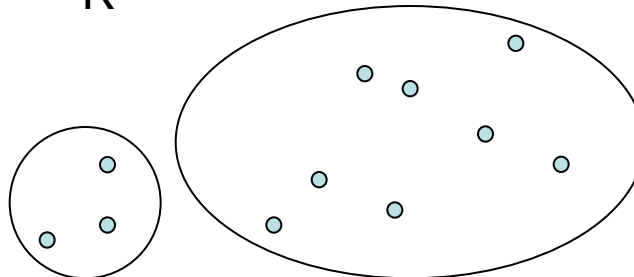
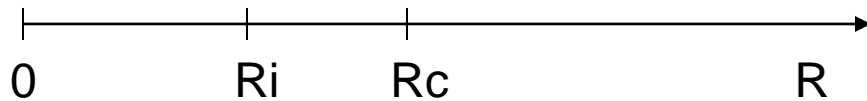
For $R = 0$ the graph is not connected.

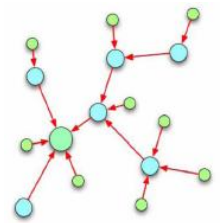
When R increases, nodes group together in clusters.

When $R = R_i$ the last isolated node disappears.

When $R = R_c$ the graph becomes connected.

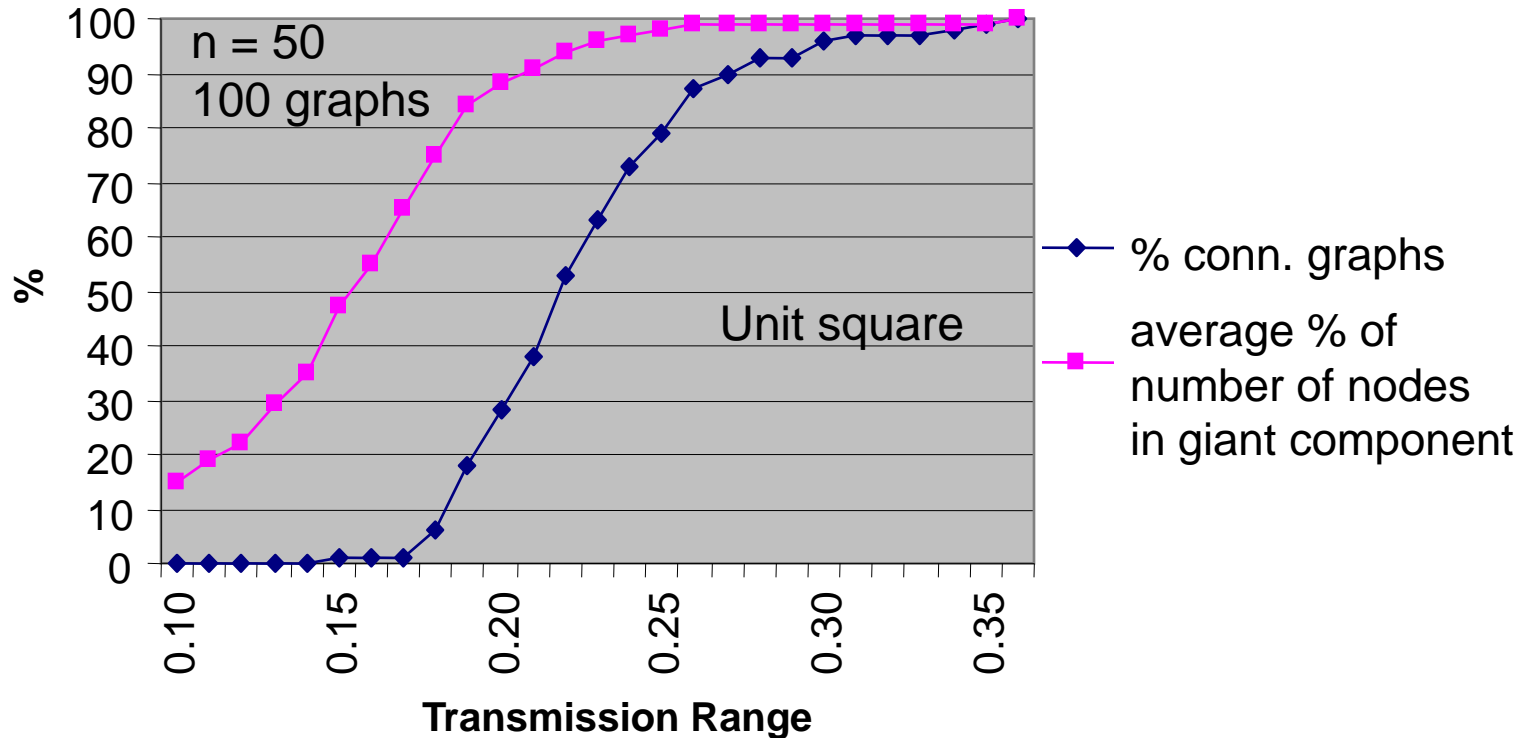
Clearly, $R_i < R_c$ as for some $R_i < R_A < R_c$ there might be a communication graph not connected even in the absence of isolated nodes (a “clustered” network with isolated clusters).

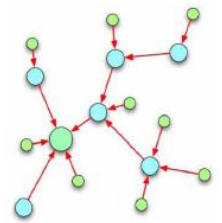




The Giant Component

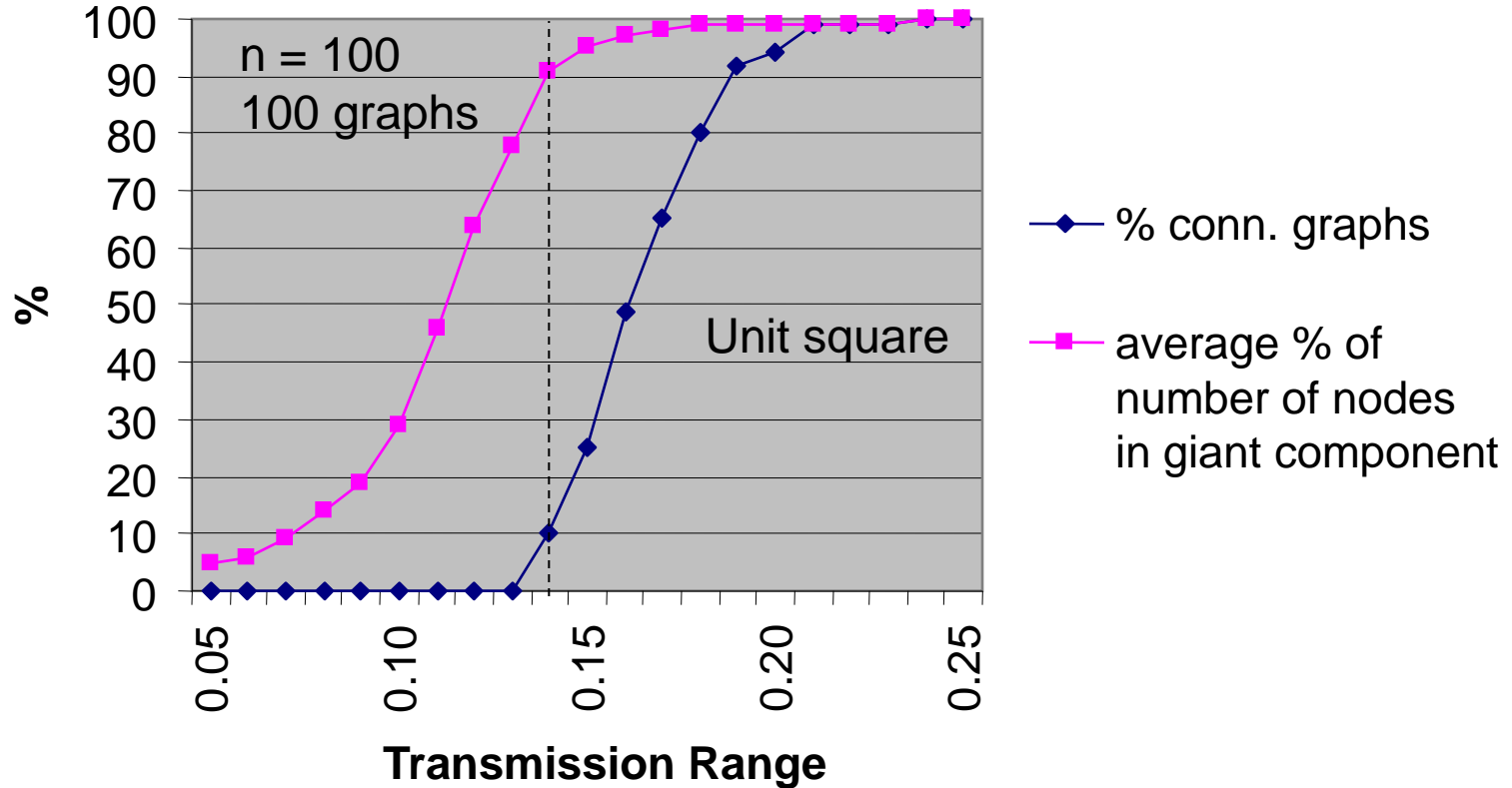
Full connectivity and giant component

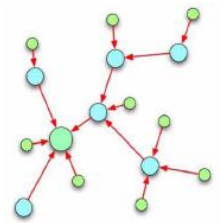




The Giant Component

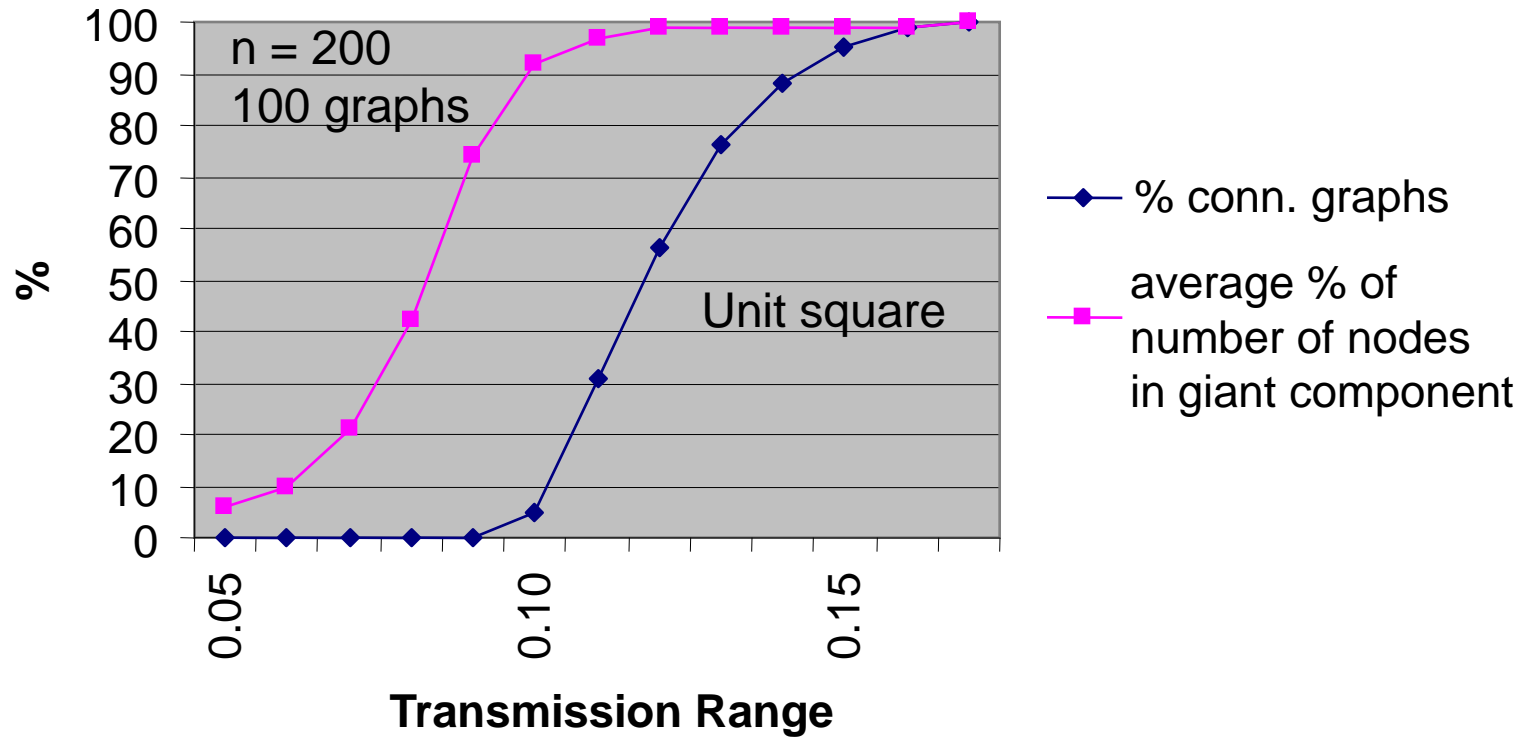
Full connectivity and giant component

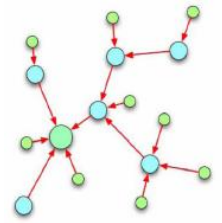




The Giant Component

Full connectivity and giant component





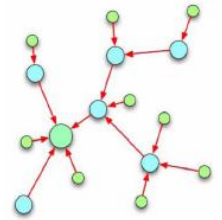
The Giant Component

The giant component is a phenomenon appearing also for practical values of n .

Therefore, it can be claimed that, approximately, for any value of n

**the probability of a Communication Graph to be connected equals
the probability of no isolated nodes.**

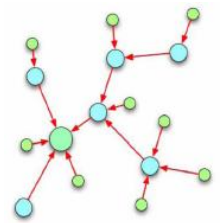
However, this approximation has not been investigated mathematically for finite n .



Section 4

Connectivity Over an Unlimited Region

John Orriss
Orriss' First Result
Modification
Orriss' Second Result
Corollary



John Orriss

IEEE TRANSACTIONS ON COMMUNICATIONS, VOL. 51, NO. 4, APRIL 2003

Probability Distributions for the Number of Radio Transceivers Which Can Communicate With One Another [1]

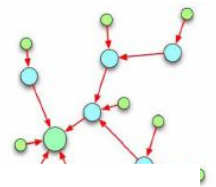
John Orriss and Stephen K. Barton, *Senior Member, IEEE*

PPP over unbounded region
omnidirectional antennas

$$L = k_0 + k_1 \ln R + S \leq t_1.$$

II. PROBABILITY DISTRIBUTION OF THE DISTANCE
SUBJECT TO A MAXIMUM LOSS

III. NUMBER OF AUDIBLE BASE STATIONS



Orriss' First Result

$$f_R(r) = 2Kr\Phi(a - b \ln r) \quad (7)$$

where $a = [k_1 - k_0 - 2\sigma^2/k_1]/\sigma$, $b = k_1/\sigma$,
 $K = \exp[-(2/k_1)[k_1 - k_0 - \sigma^2/k_1]]$, and
 $\Phi(x) = \int_{-\infty}^x (1/\sqrt{2\pi})e^{-u^2/2} du$.

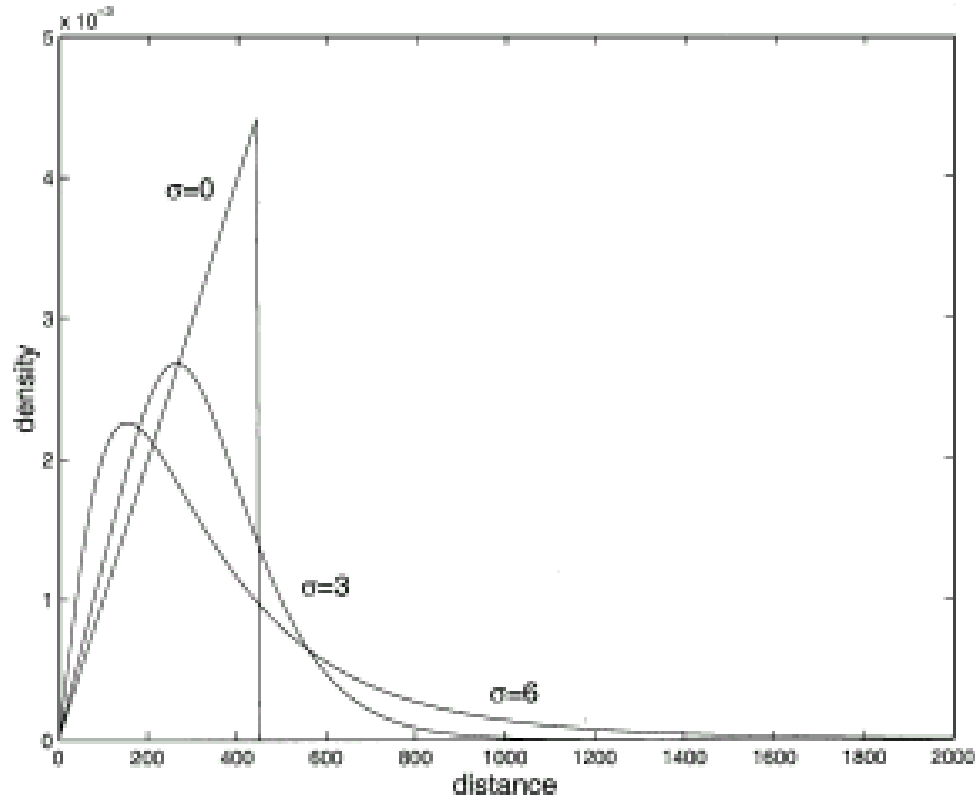
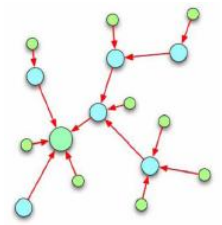


Fig. 1. PDF of distance between communicating nodes.



Modification

Orriss:

$$f_R(r) = 2Kr\Phi(a - b \ln r) \quad \text{where}$$

$$a = [L_{th} - k_0 - 2\sigma^2/k_1]/\sigma,$$

$$b = k_1/\sigma$$

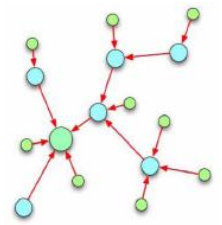
$$K = \exp[-(2/k_1)[L_{th} - k_0 - \sigma^2/k_1]],$$

$$\Phi(x) = \int_{-\infty}^x (1/\sqrt{2\pi})e^{-u^2/2}du.$$

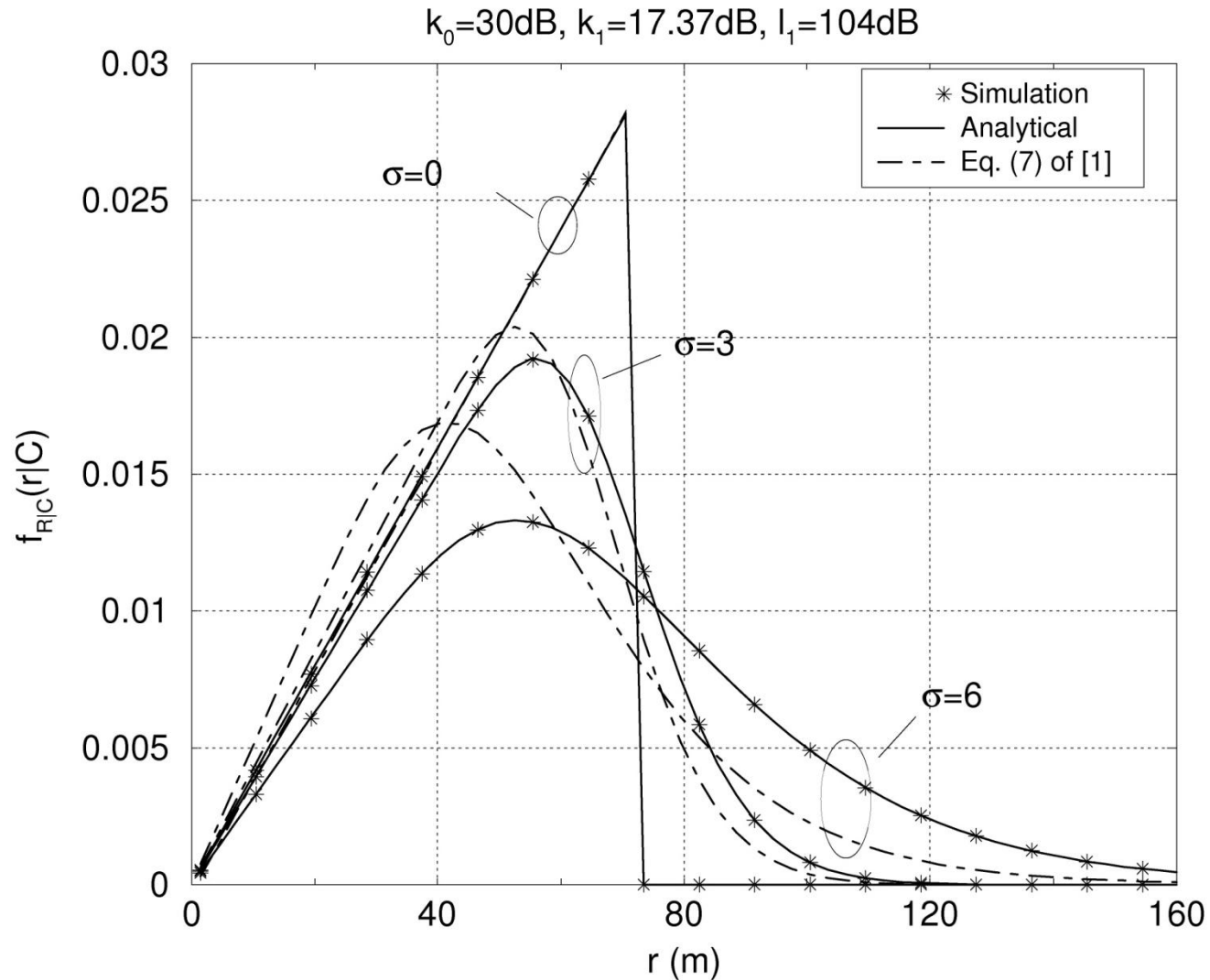
Correct expression:

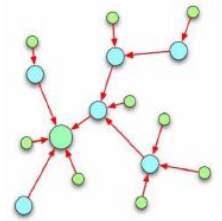
$$f_{R|C}(r|C) = r e^{-\frac{2}{k_1}(l_1 - k_0 - \sigma^2/k_1)} \operatorname{erfc} \left(\frac{k_0 - l_1 + k_1 \ln r}{\sqrt{2}\sigma} \right)$$

where $\operatorname{erfc}(\cdot)$ denotes the complementary error function.



Modification



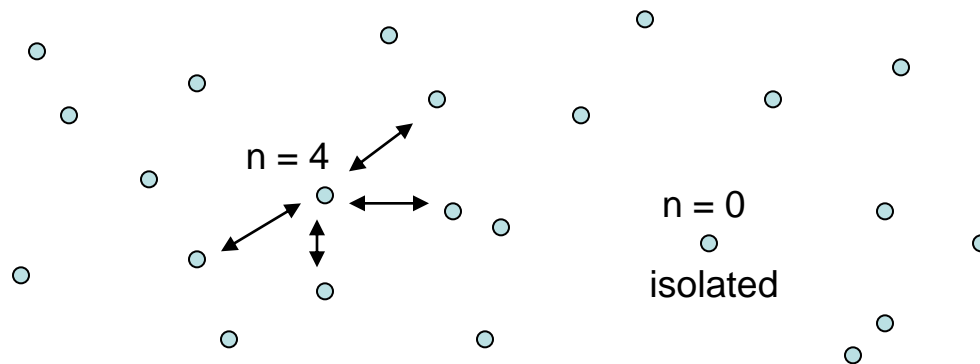


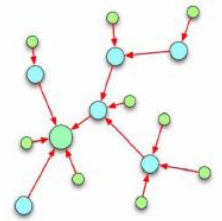
Orriss' Second Result

The number of nodes heard by a given node is Poisson, with mean

$$Nm = \rho \pi \exp(2 (l_1 - k_0) / k_1) \exp(2\sigma^2 / k_1^2)$$

Then, the probability of a node to be isolated is $P(\text{iso}) = \exp(-Nm)$.



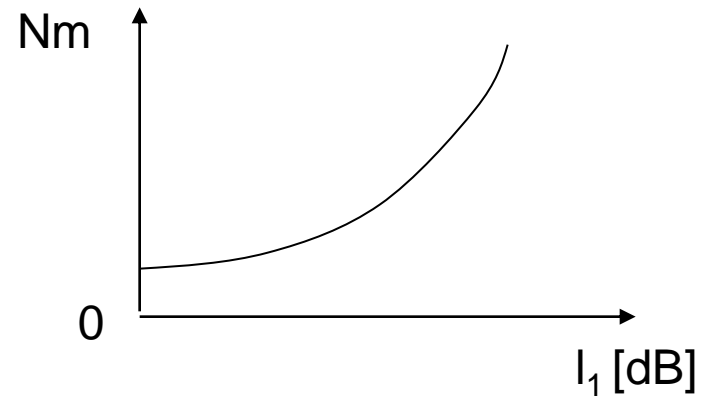
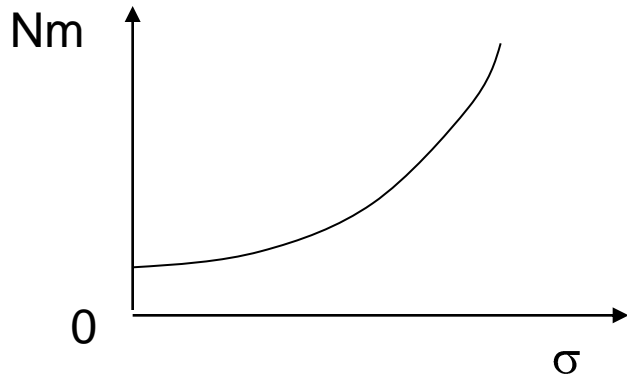


Orriss' Second Result

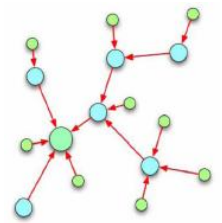
Note: N_m is linearly proportional to node density
 N_m is quadratically proportional to the ideal transmission range R :
$$N_m = \rho \pi R^2 \exp(2\sigma^2 / k_1^2)$$

N_m is exponentially proportional to the variance of shadowing

N_m is exponentially proportional to transmit power: $I_1 = P_t - P_{rmin}$



Channel fluctuations may significantly increase network connectivity

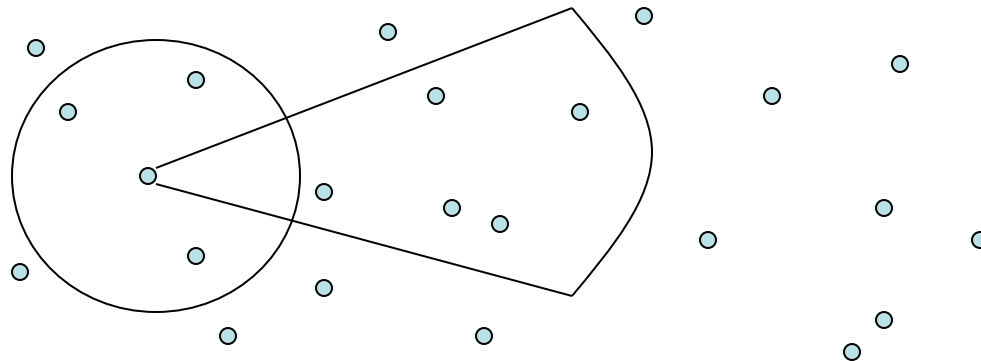


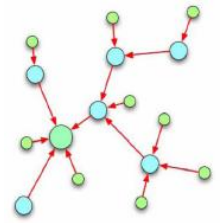
Corollary

The number of nodes heard by a given node is Poisson, with mean

$$Nm = \rho \pi \exp(2(l_1 - k_0) / k_1) \exp(2\sigma^2 / k_1^2)$$

Do randomly directed directional antennas help increasing connectivity?





Corollary

The number of nodes heard by a given node is Poisson, with mean

$$Nm = \rho \pi \exp(2(l_1 - k_0) / k_1) \exp(2\sigma^2 / k_1^2)$$

Do randomly directed directional antennas help increasing connectivity?

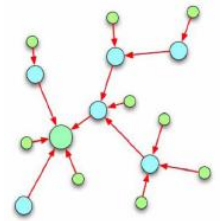
Denoting $Nm = Nm(G)$ the mean as a function of antenna gain, implicitly included in k_0 , then with directional antennas

$$\begin{aligned} Nm(G) &= (1 / G) \rho \pi \exp(2(l_1 - k_0 + 10\log G) / k_1) \exp(2\sigma^2 / k_1^2) \\ &= Nm(1) \exp(20\log G) / k_1) / G \end{aligned}$$

Therefore the ratio $Nm(G) / Nm(1) = \exp(20\log G) / k_1) / G$ measures the advantage of using directional antennas.

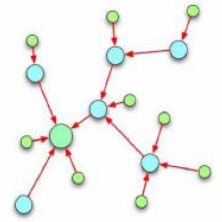
For example:

$G = 4$ [6 dB], $k_1 = 13.3 \rightarrow Nm(G) / Nm(1) = 0.62 \rightarrow$ **connectivity is decreased!**



Section 5

Connectivity for WSNs



Full Connectivity

Traditional definition:

A network is fully connected if there exists any path (sequence of hops) between every pair of nodes.

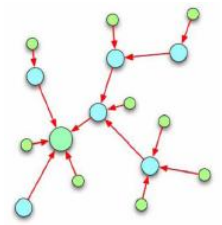
This definition is compliant with the objective of ad hoc networks, i.e. to allow every node being in contact with any other node.

But this is not the goal of a WSN.

In WSNs, nodes (sensors) want to transmit their samples to a given node, namely, the sink (or any node in a given set, in the case of multi-sink networks).

Definition more suitable for WSNs:

A WSN is fully connected if all nodes can report their samples to a sink through any path.



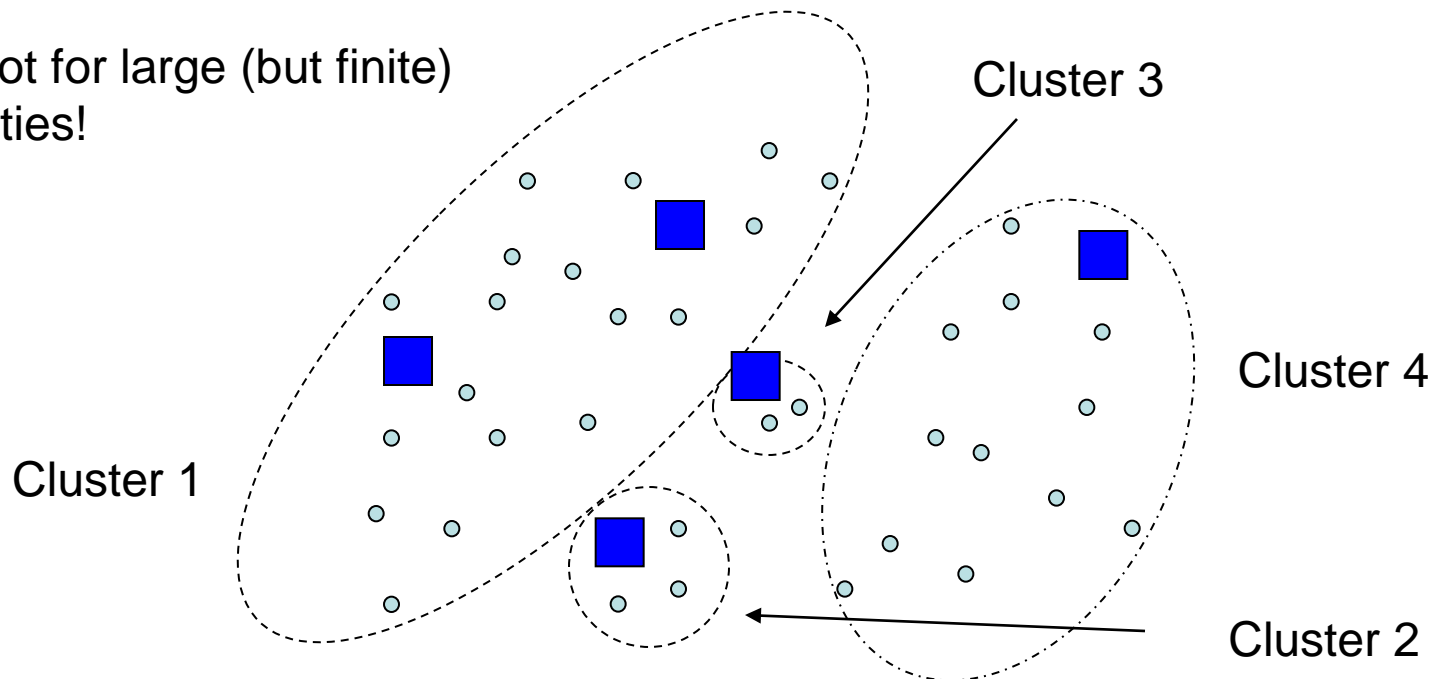
Full Connectivity

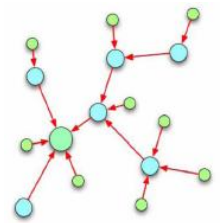
A WSN is fully connected if all nodes can report their samples to a sink through any path.

No difference in a single-sink scenario

Difference in a multi-sink scenario

But not for large (but finite)
densities!





Full Connectivity: approximated analysis

Probability of a network of area A , given n_0 nodes in A , being fully connected:

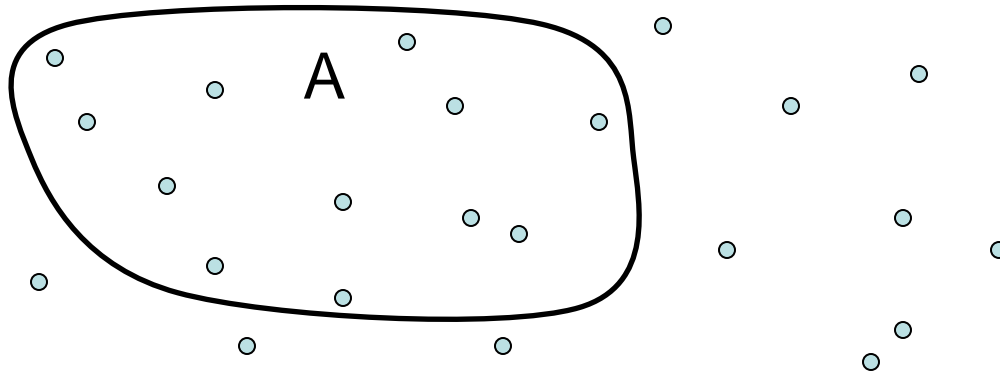
$$P(\text{con} \mid n_0) \approx P(\text{no isolated nodes in } A \mid n_0) \approx (1 - P(\text{iso}))^{n_0}$$

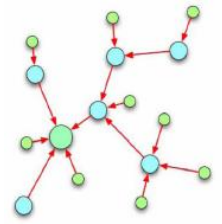
(1) (2)

- (1) If network is dense: indeed, $P(\text{con}) \leq P(\text{no isolated nodes in } A)$
- (2) If $P(\text{iso})$ is small and network is dense

Dense network:
 $P(\text{iso})$ small:

$\rho A \gg 1$
 $P(\text{iso}) \ll 0.001$



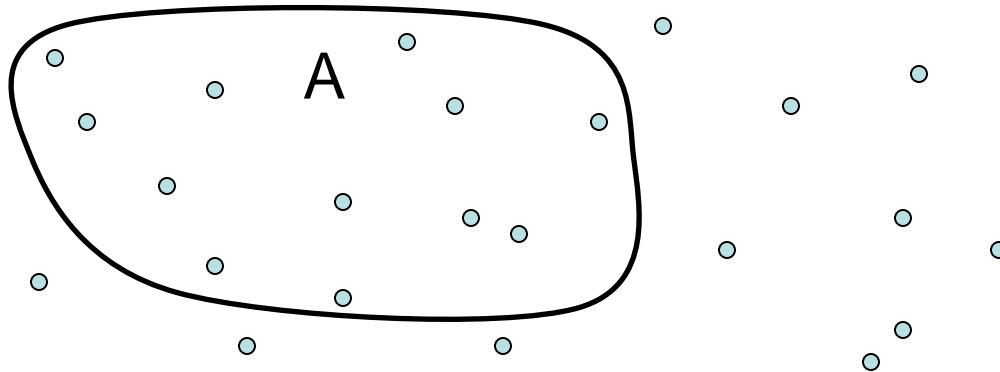


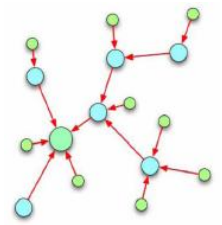
Full Connectivity: approximated analysis

Probability of a network of area A being fully connected:

$$\begin{aligned}
 P(\text{con}) &= E_{n_0} [P(\text{con} \mid n_0)] = E_{n_0} [(1 - P(\text{iso}))^{n_0}] = \dots \\
 &= \exp [- \rho A \exp(- Nm)] \quad Nm = \pi \rho e^{2\left(\frac{\sigma^2}{k_1^2} - \frac{k_0}{k_1}\right)} e^{2\left(\frac{L_{th}}{k_1}\right)} \quad [L_{th} = l1]
 \end{aligned}$$

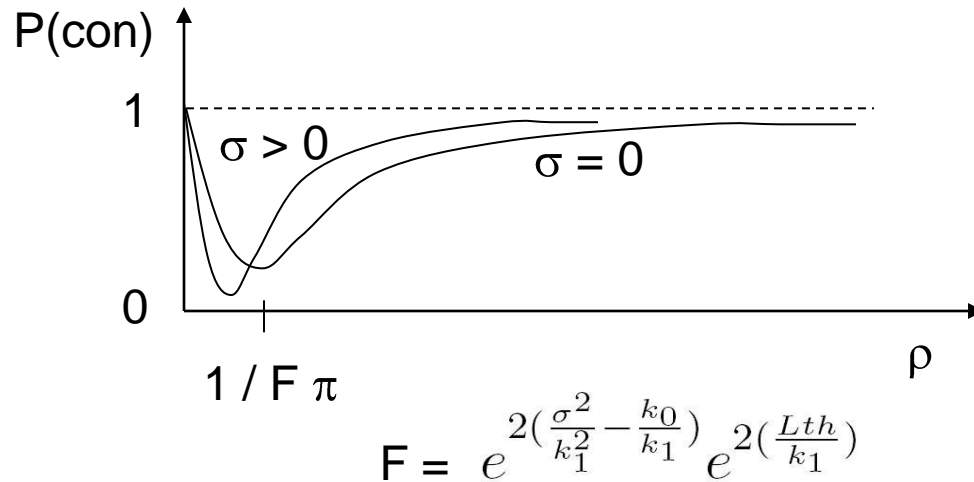
Note: A must be large $\rightarrow A \gg \pi R^2$

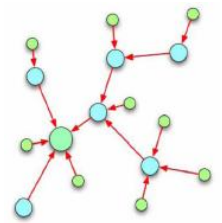




Full Connectivity: approximated analysis

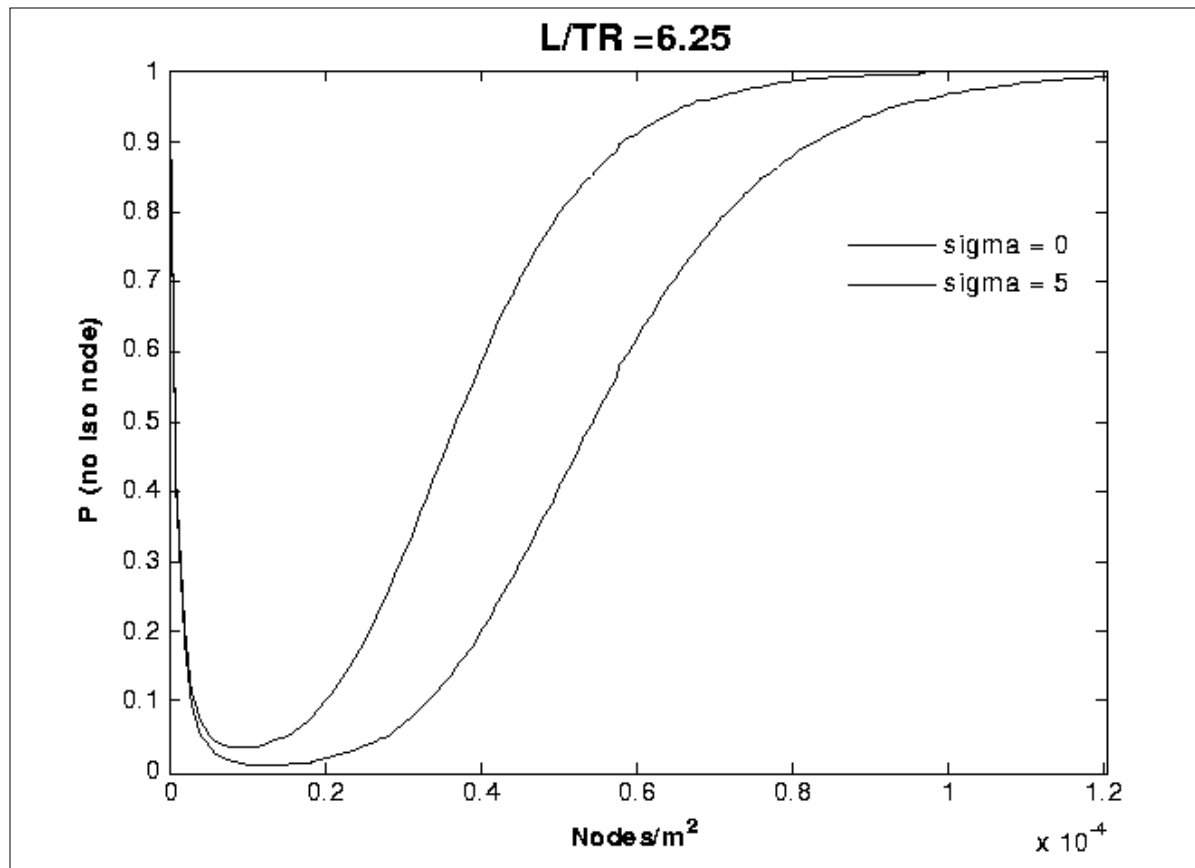
Probability of a network of area $A = L^2$ being fully connected



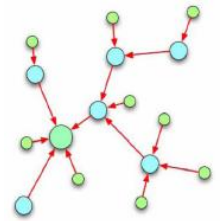


Full connectivity: approximated analysis

Probability of a network of area $A = L^2$ being fully connected. TR is ideal trans. range



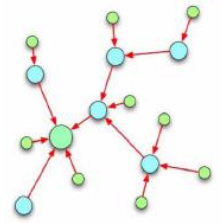
Channel fluctuations significantly reduce the number of required nodes



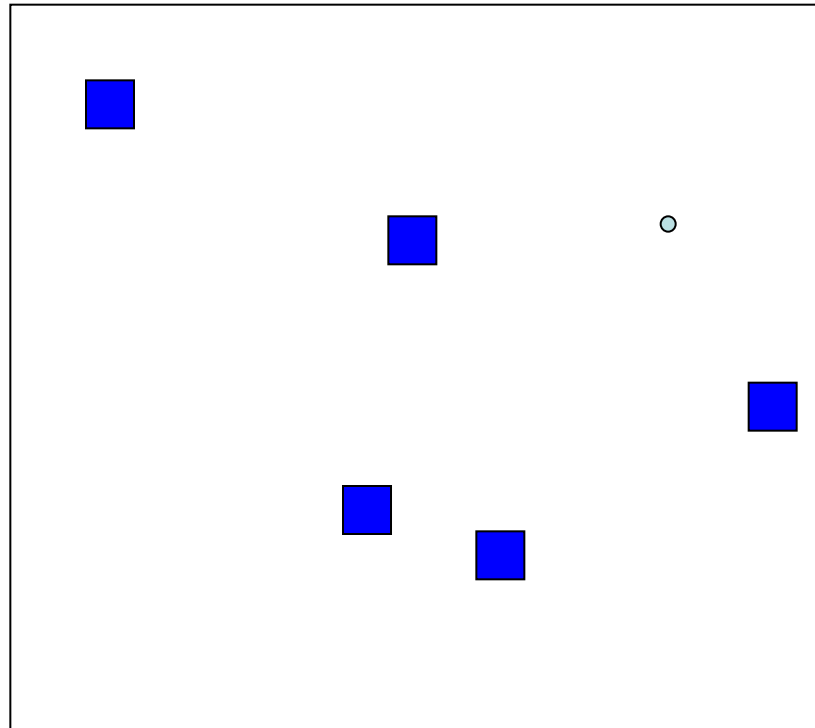
Section 6

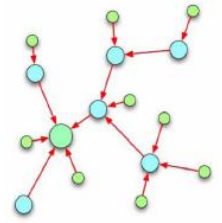
Connectivity Over Limited Regions for WSNs

- Connectivity in Squares
- Full Connectivity in Squares – Single Hop
- Reachability in Squares – Single Hop
- Reachability in Squares – Multiple Hops, Tree Topologies

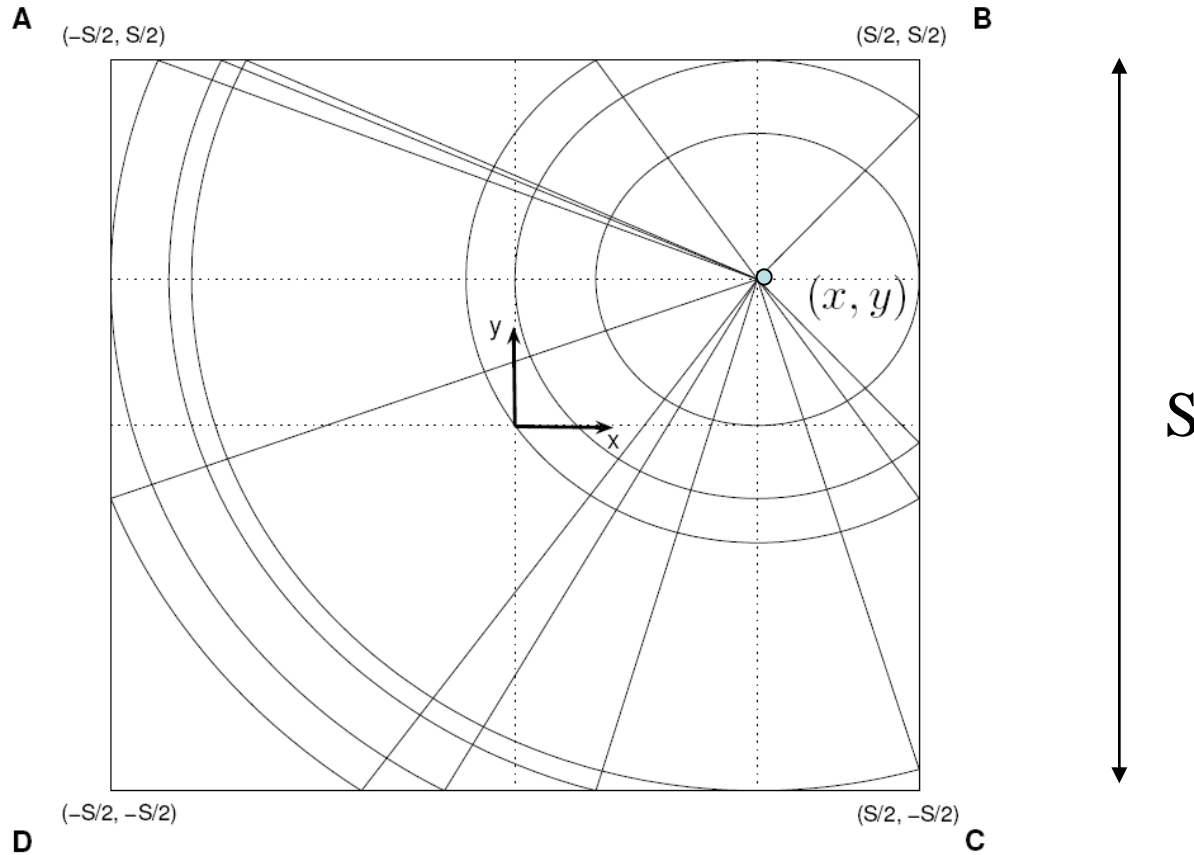


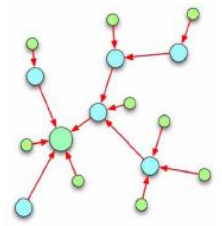
Connectivity in Squares





Connectivity in Squares





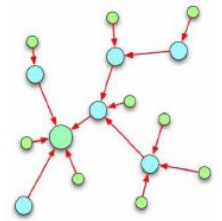
Connectivity in Squares

Number of sinks heard from a node in (x,y) is Poisson with mean

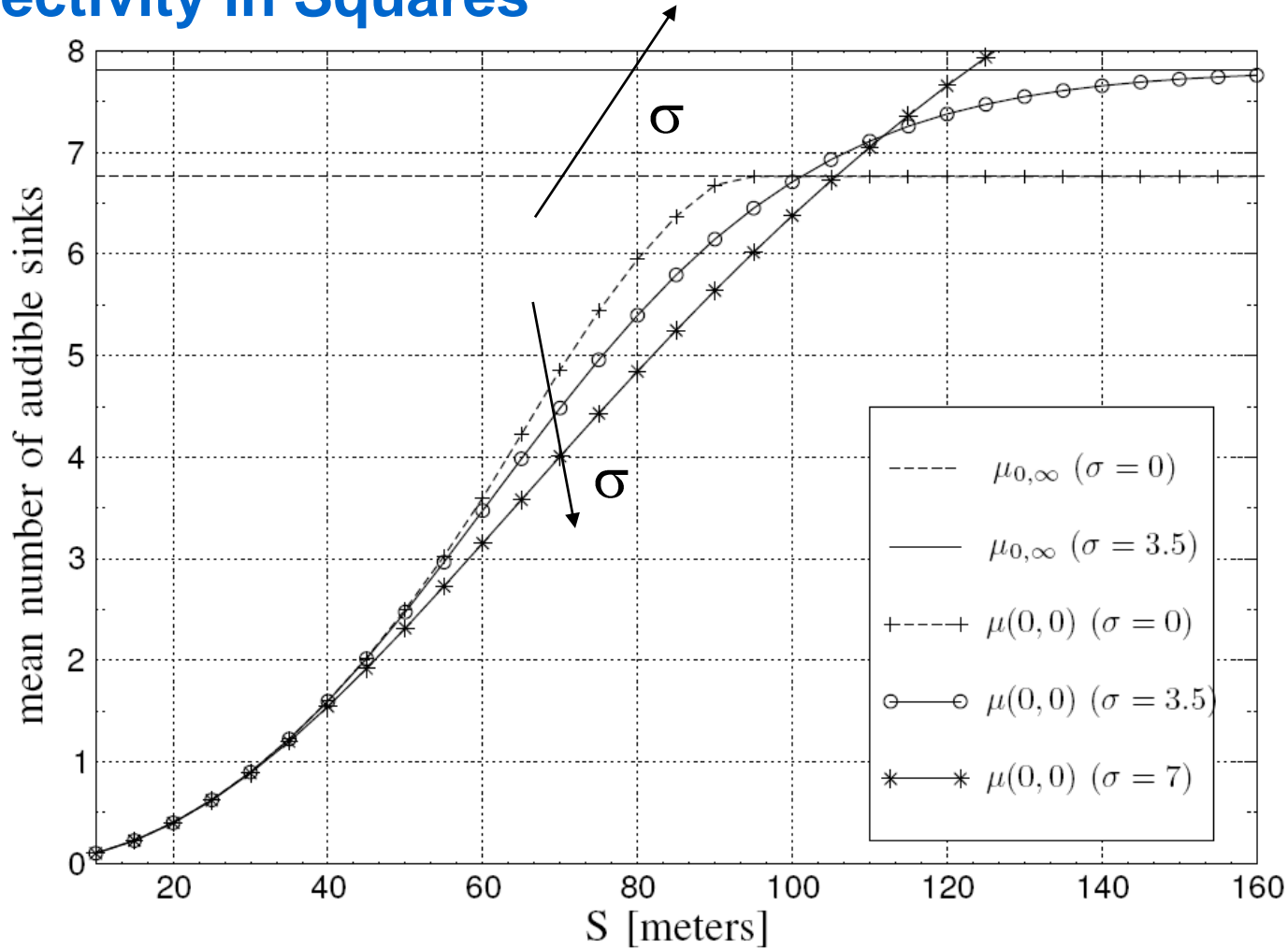
$$\mu(x, y) = \sum_{i=1}^8 \int_{r_{1,i}}^{r_{2,i}} 2\theta_i(r) \cdot \rho_0 \cdot r \cdot \Phi(a_1 - b_1 \ln r) dr.$$

Region	Range: $r_1 \leq r \leq r_2$
1	$0 \leq r \leq \frac{S}{2} - x$
2	$\frac{S}{2} - x \leq r \leq \frac{S}{2} - y$
3	$\frac{S}{2} - y \leq r \leq \sqrt{(\frac{S}{2} - x)^2 + (\frac{S}{2} - y)^2}$
4	$\sqrt{(\frac{S}{2} - x)^2 + (\frac{S}{2} - y)^2} \leq r \leq \frac{S}{2} + y$
5	$\frac{S}{2} + y \leq r \leq \sqrt{(\frac{S}{2} - x)^2 + (\frac{S}{2} + y)^2}$
6	$\sqrt{(\frac{S}{2} - x)^2 + (\frac{S}{2} + y)^2} \leq r \leq \frac{S}{2} + x$
7	$\frac{S}{2} + x \leq r \leq \sqrt{(\frac{S}{2} + x)^2 + (\frac{S}{2} - y)^2}$
8	$\sqrt{(\frac{S}{2} + x)^2 + (\frac{S}{2} - y)^2} \leq r \leq \sqrt{(\frac{S}{2} + x)^2 + (\frac{S}{2} + y)^2}$

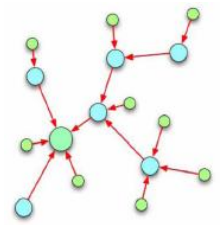
Region	$\theta(r)$
1	π
2	$\frac{\pi}{2} + \arcsin \frac{\frac{S}{2} - x}{r}$
3	$\frac{\pi}{2} + \arcsin \frac{\frac{S}{2} - x}{r} - \arccos \frac{\frac{S}{2} - y}{r}$
4	$\frac{\pi}{2} + \frac{1}{2} (\arcsin \frac{\frac{S}{2} - x}{r} - \arccos \frac{\frac{S}{2} - y}{r})$
5	$\frac{\pi}{2} - \arccos \frac{\frac{S}{2} + y}{r} + \frac{1}{2} (\arcsin \frac{\frac{S}{2} - x}{r} - \arccos \frac{\frac{S}{2} - y}{r})$
6	$\frac{\pi}{2} - \frac{1}{2} (\arccos \frac{\frac{S}{2} + y}{r} + \arccos \frac{\frac{S}{2} - y}{r})$
7	$\frac{1}{2} (\arcsin \frac{\frac{S}{2} - y}{r} + \arcsin \frac{\frac{S}{2} + y}{r}) - \arccos \frac{\frac{S}{2} + x}{r}$
8	$\frac{1}{2} (\arcsin \frac{\frac{S}{2} + y}{r} - \arccos \frac{\frac{S}{2} + x}{r})$



Connectivity in Squares



Channel fluctuations increase network connectivity only in unlimited region



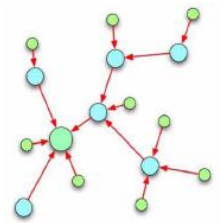
Full Connectivity in Squares – Single Hop

$$q(x, y) = 1 - \exp(-\mu(x, y))$$

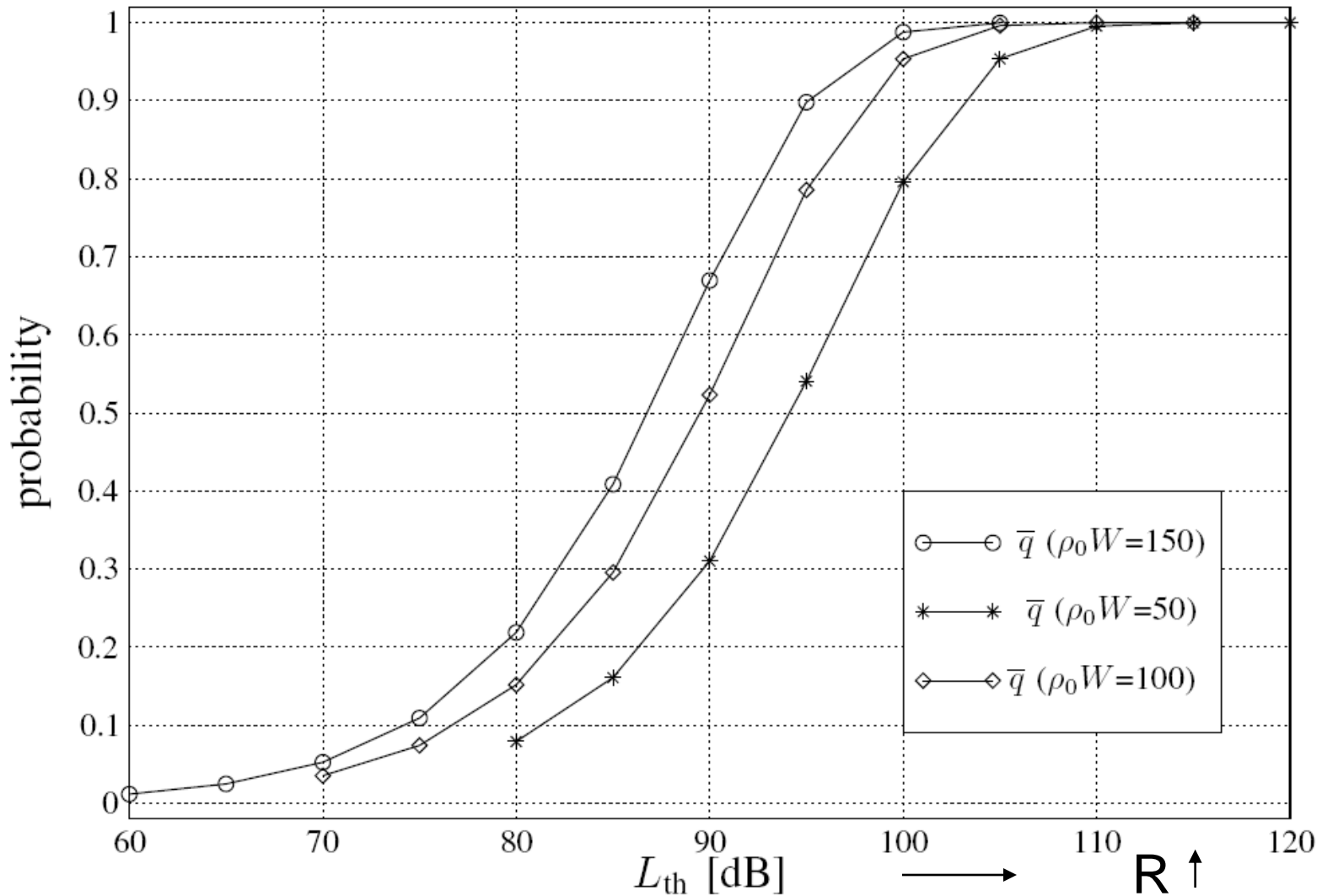
$$\bar{q} = \frac{8}{W} \int_0^{S/2} \int_0^x q(x, y) dy dx$$

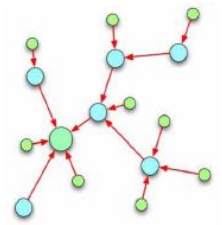
$$\text{Prob} \{F | N_s = k\} = \bar{q}^k$$

$$\begin{aligned} Z = \text{Prob} \{F\} &= \sum_{k=1}^{+\infty} \text{Prob} \{F | N_s = k\} \text{Prob} \{N_s = k\} \\ &= \sum_{k=1}^{+\infty} \bar{q}^k \cdot \frac{e^{-\rho_s W}}{k!} (\rho_s W)^k \end{aligned}$$



Full Connectivity in Squares – Single Hop



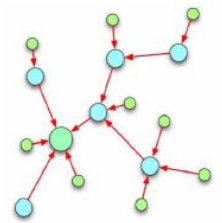


Reachability in Squares – Single Hop

In some applications, Full Connectivity is not required

A sufficient degree or reachability is requested i.e. a given minimum number of sensors needs to reach the sinks

$$Z_{\bar{m}}(j) = \text{Prob} \{C_j\} = e^{-\bar{m}} \cdot \sum_{k=j}^{+\infty} \sum_{l=j}^k \binom{k}{l} \frac{\bar{m}^k \bar{q}^l (1 - \bar{q})^{k-l}}{k!}$$



Reachability in Squares – Single Hop

